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HARMO 22

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SOURCE RECONSTRUCTION BASED ON INVERSE MODELLING WITH DEPOSITION MEASUREMENTS

Belgian Nuclear Research Centre

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CASE STUDY // Undisclosed ¹⁰⁶Ru release in 2017



Observations

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- September October 2017
- air concentration (up to 180 mBq/m³) and deposition (up to 90 Bq/m²) in Europe

Source term from previous literature

- location → Mayak nuclear installation
- **release** \rightarrow 200 500 TBq (1.6 4 g ¹⁰⁶Ru)
- based on air concentration measurements

CASE

Location of deposition detections



P Research question

Theoretically, can (mobile, cheap) wet deposition measurements be used to complement (fixed, expensive) air concentration measurements for the purpose of inverse modelling?

MODELS

ELS U

OBJECTIVES METHODS





THEORY // Inverse modelling

 source-receptor-sensitivity M_{ij} is the sensitivity of observation y_i to source term x_j

$$y_i = \sum_j M_{ij} x_j$$

- only need to **calculate** M_{ij} 's once to generate y_i for any x_j
- we consider y as either **air concentration** (Bq/m³) or **deposition** (Bq/m²) \rightarrow different SRS fields M_{ij} for each quantity



THEORY // Air concentration and deposition have different physical implications for inverse modelling



MODELS // Flexpart + FREAR

- ATM → Flexpart v10 (Pisso et al. 2019) in backward-in-time mode (Seibert et al. 2004, Eckhardt et al. 2017)
- inverse modelling code → FREAR (*De Meutter and Hoffman 2020*), open-source

FREAR v1

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Input	 SRS fields from ATM (Flexpart) environmental observations (air concentration) 			
Methods	 cost function optimisation Bayesian inference possible source region field of regard 		More info at • H22-066 (presentation)	
Output	 Source term release location (probability) release amount release timing 		• H22-079 (poster)	
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CASI	THEORY MODELS	OBJECTIVES	METHODS	RESUL



OBJECTIVES // Adding deposition to FREAR

• **FREAR v1** uses activity air concentration

$$c = M_c \cdot x$$

• **new implementation** for this study

$$\begin{bmatrix} c \\ d_{\text{wet}} \\ d_{\text{dry}} \\ d_{\text{tot}} \end{bmatrix} = \begin{bmatrix} M_c \\ M_{d_{\text{wet}}} \\ M_{d_{\text{dry}}} \\ M_{d_{\text{dry}}} \end{bmatrix} \cdot x$$

→ inverse modelling with multiple types of measurements simultaneously!
 (any combination)



METHODS // Experiments

Twin experiment

- 1. forward ATM calculation with ¹⁰⁶Ru source term (*Saunier et al. 2019*)
- 2. generate synthetic observations
- 3. inverse modelling with synthetic observations
- → eliminates model- & observational errors

CASE

THEORY

MODELS

Real data

OBJECTIVES

- inverse modelling with real observations
- observational data from Masson et al. (2019)



METHODS

RESULTS

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METHODS // Observations per experiment





Bayesian inference

Wet deposition

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CASE

THEORY

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Source location probability 0.05 65 0.04 Latitude (°) 22 0.03 0.02 50 0.01 0 45 45 65 70 75 40 50 55 60 Longitude (°)



Real data

MODELS OBJECTIVES METH

METHODS //

RESULTS

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Bayesian inference

Total (wet+dry) deposition



CASE

THEORY

//

MODELS

OBJECTIVES



METHODS

//

RESULTS

////



Real data

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Real data



Bayesian inference





OBJECTIVES

RESULTS METHODS //

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Bayesian inference



Air concentration



Wet + total deposition





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OBJECTIVES

METHODS

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RESULTS

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CONCLUSIONS

✓ Source reconstruction & localisation with deposition measurements is possible.

- This demonstrates that (mobile, cheap) wet dep measurements can theoretically be used to complement (fixed, expensive) air concentration measurements for the purpose of inverse modelling.
- Wet deposition measurements seem to contain less 'information' compared to air concentration (see twin experiment), but still provide very good results (see real data).

 Localisation with real data of total deposition seems to work less well (in this case + dataset).





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Wet deposition

Cost function optimisation









Real data

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