

# Refining Urban Wind and Pollutant Dispersion Modelling: From Airborne Lidar Data to CFD Models

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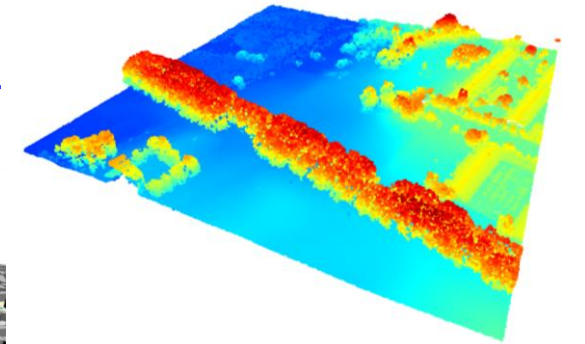
# Outline

- Introduction & Objective
- Building reconstruction
- CFD Simulations (RANS)
- Wind Scanner Campaign (Validation)
- Initial Results
- Conclusions and Outlook

DTU Risø Campus



Point Cloud Data



URD Dispersion Model



# Introduction & Objective

Predicting both high-resolution wind patterns and atmospheric dispersion of pollutants is challenging in urban areas due to the complexity of the urban canopy.

## Challenges:

- Difficulty in obtaining realistic urban geometry for flow models
- Need for a fine computational grid to capture building details and cover urban flow scales
- Lack of validation data matching model capabilities

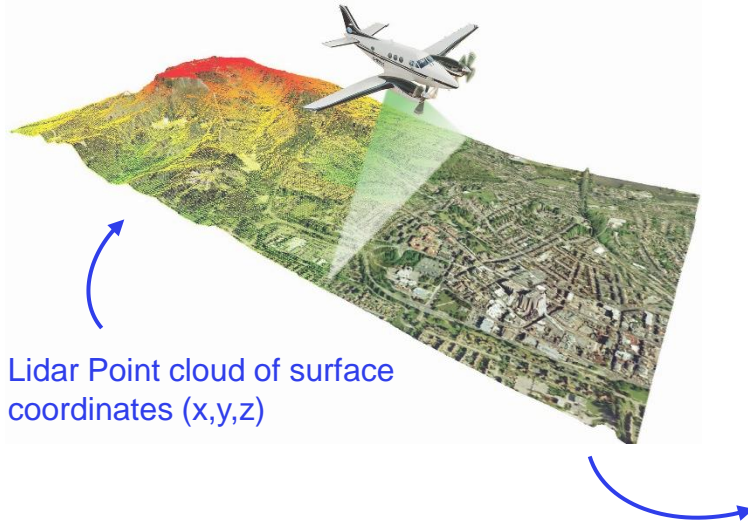
## Objective:

- Single house study to investigate the challenges and establish validation for our CFD and dispersion simulations





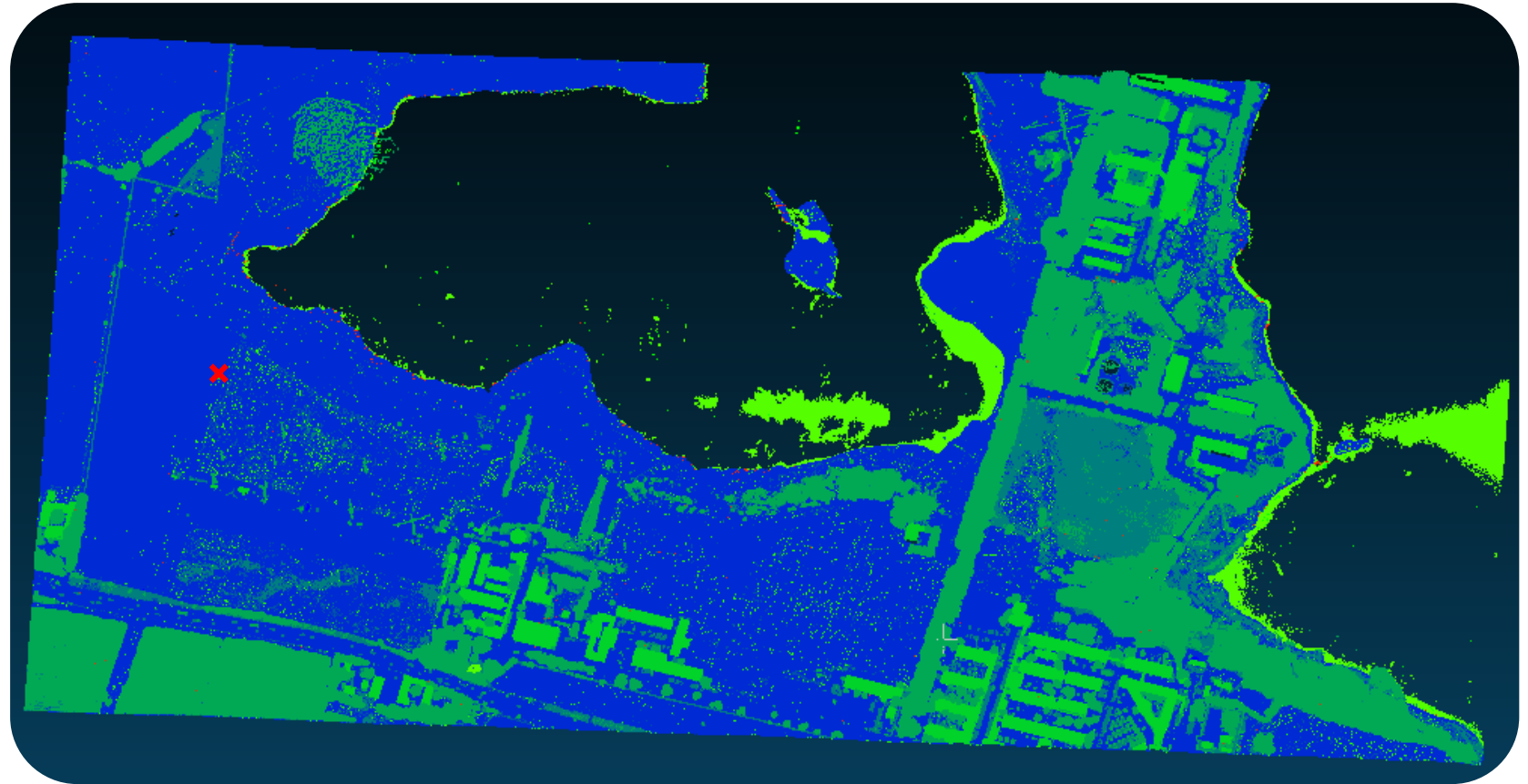
# Airborne Lidar data



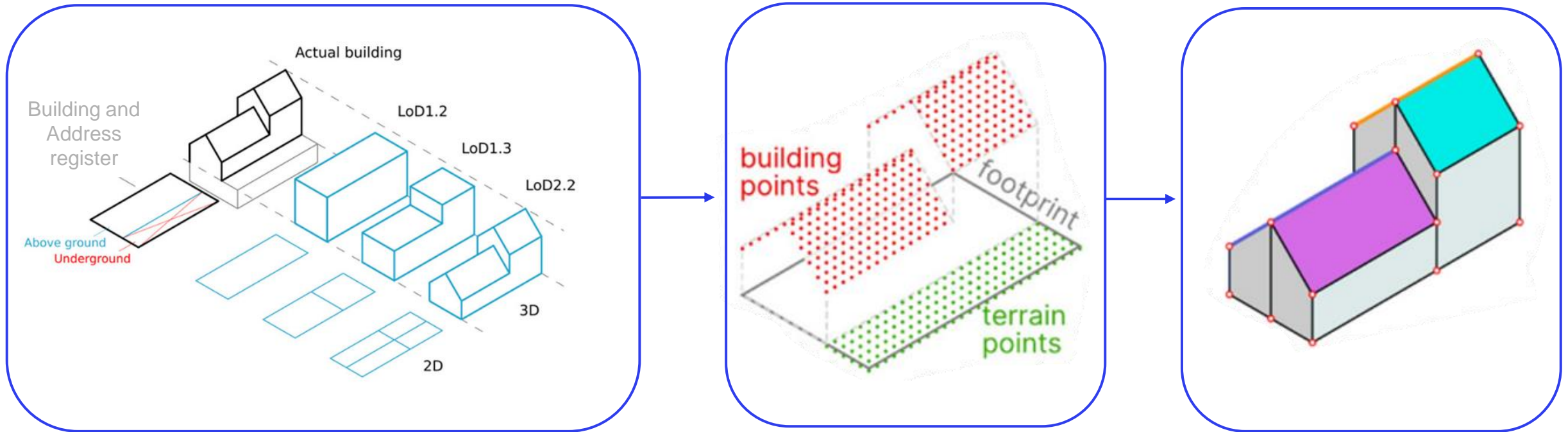
Lidar Point cloud of surface coordinates (x,y,z)

## Airborne Lidar System:

- Laser scanner, an IMU (Inertial Measurement Unit), and a GPS (Global Positioning System) attached to airplane



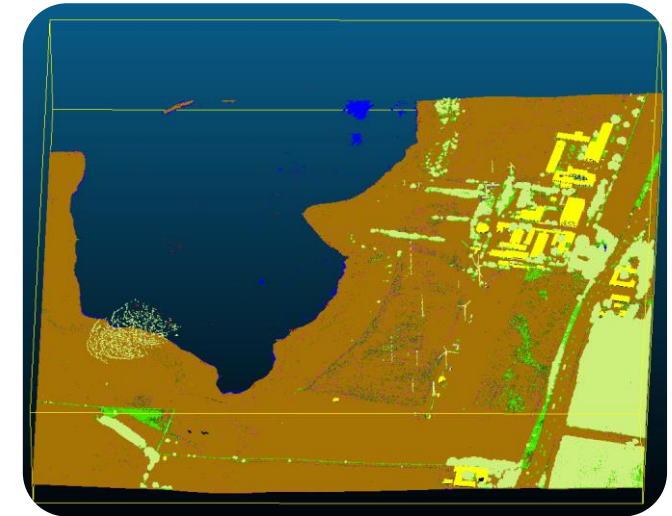
# Geoflow TU Delft - Highly realistic 3D reconstruction



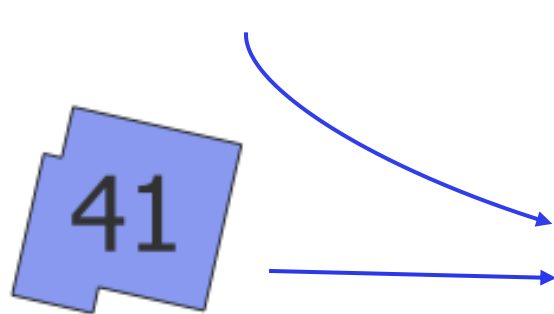
*R. Peters, B. Dukai, S. Vitalis, J. van Liempt, and J. Stoter. (2022). Automated 3D Reconstruction of LoD2 and LoD1 Models for All 10 Million Buildings of the Netherlands. Photogrammetric Engineering and Remote Sensing, 88(3), 165–170.*

# Single building reconstruction

Airbone Lidar Pointcloud

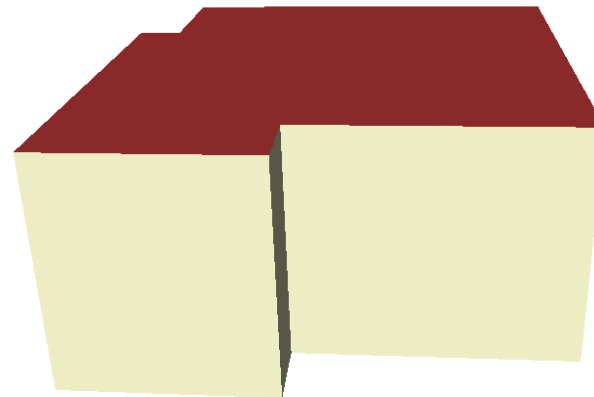


~20 min to process a 1km<sup>2</sup> pointcloud area in 3 LoDs

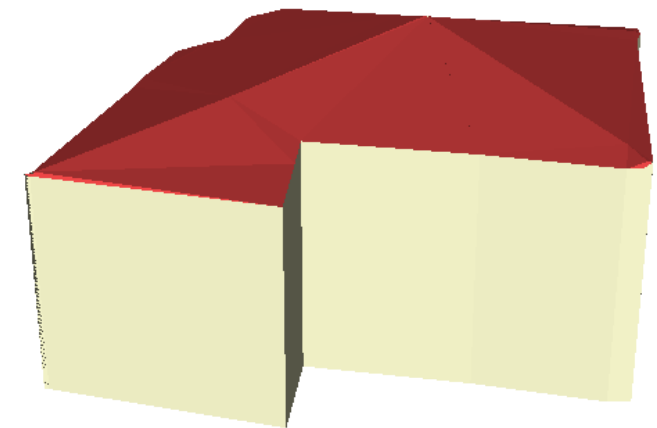


Georeferenced building footprint

LoD 1.2



LoD 2.2

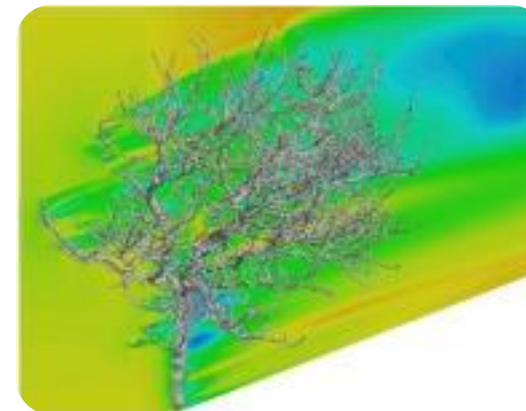
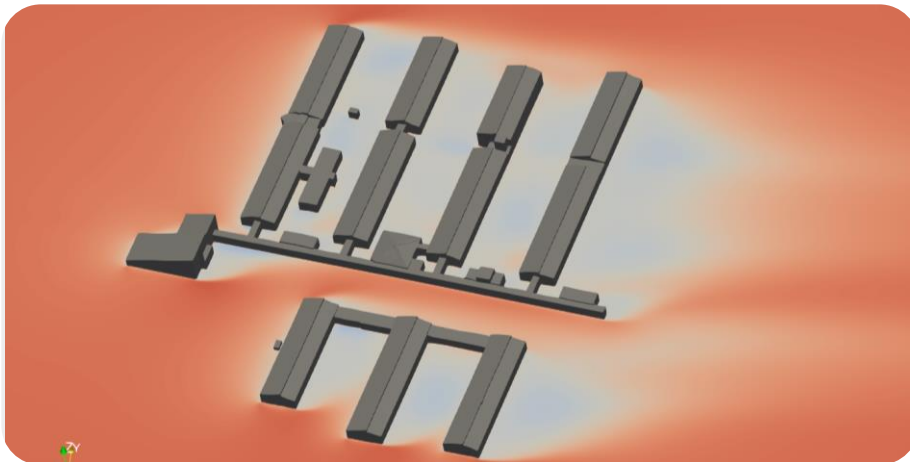
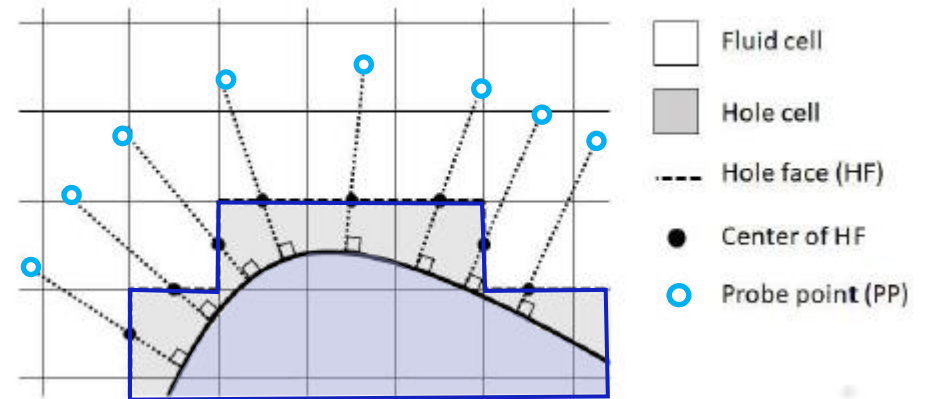




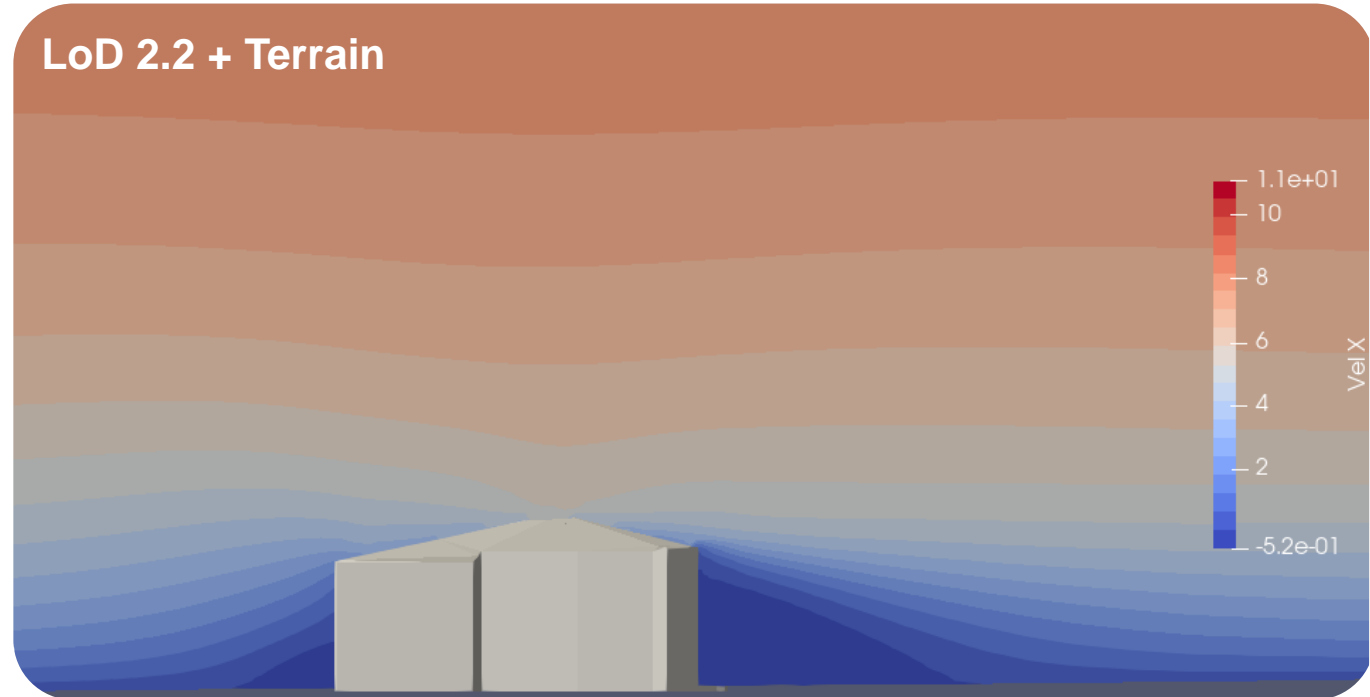
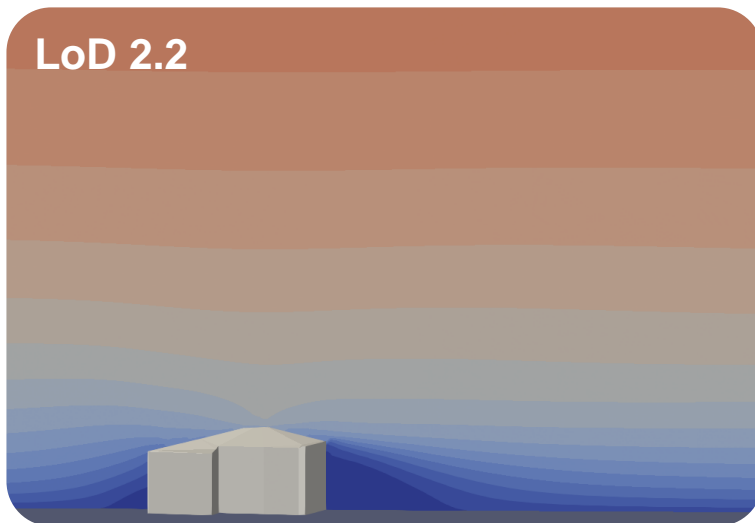
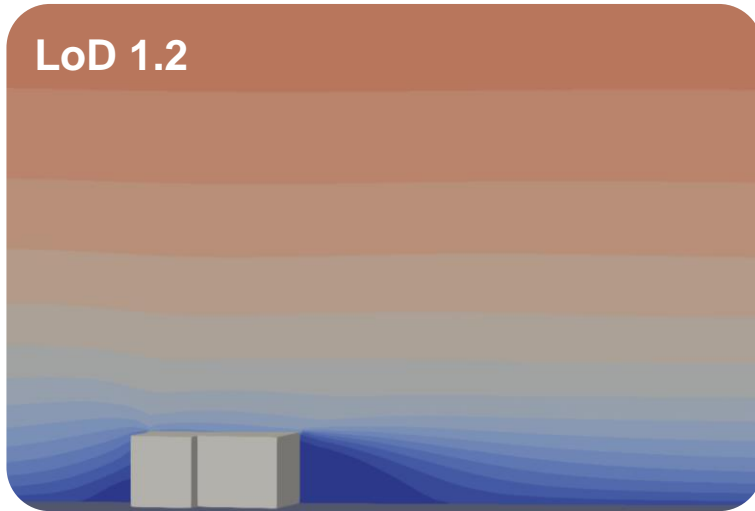
# Immersed Boundary Method (Troidborg et al., 2021)

A method for CFD to represent surfaces on non-conforming grids in EllipSys3D (RANS):

- IB → watertight surface composed of unstructured triangles
- Cut hole in background CFD grid; enclosing the IB
- Impose boundary conditions for all governing equations on the hole faces (HFs)
- Flow not solved inside object/hole
- Probe points (PPs) defined at a distance from the IB



# Simulation results – EllipSys3D RANS

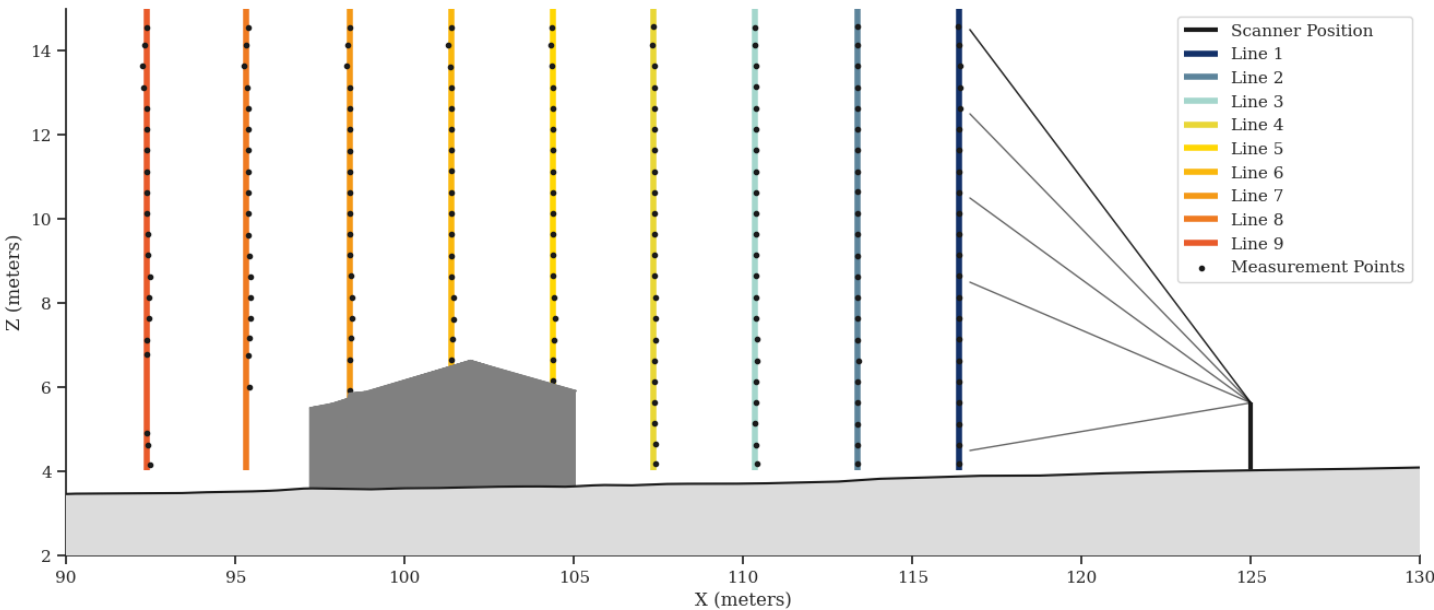


	LoD 1.2	LoD 2.2	LoD 2.2 + Terrain
<b>F<sub>x</sub> [N]</b>	232.231	185.6319	243.5852
<b>F<sub>y</sub> [N]</b>	-13.88692	-10.84574	-15.27790

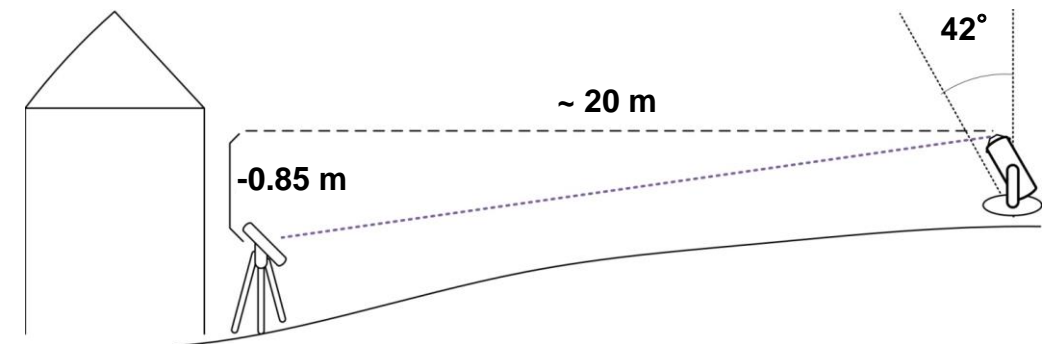


# Wind Scanner Campaign

- Experiment took place in summer 2011
- DTU short-range Wind Scanner
- Continuous Wave Lidar with a sampling frequency  $\sim 390$  Hz
- Line scanning pattern:

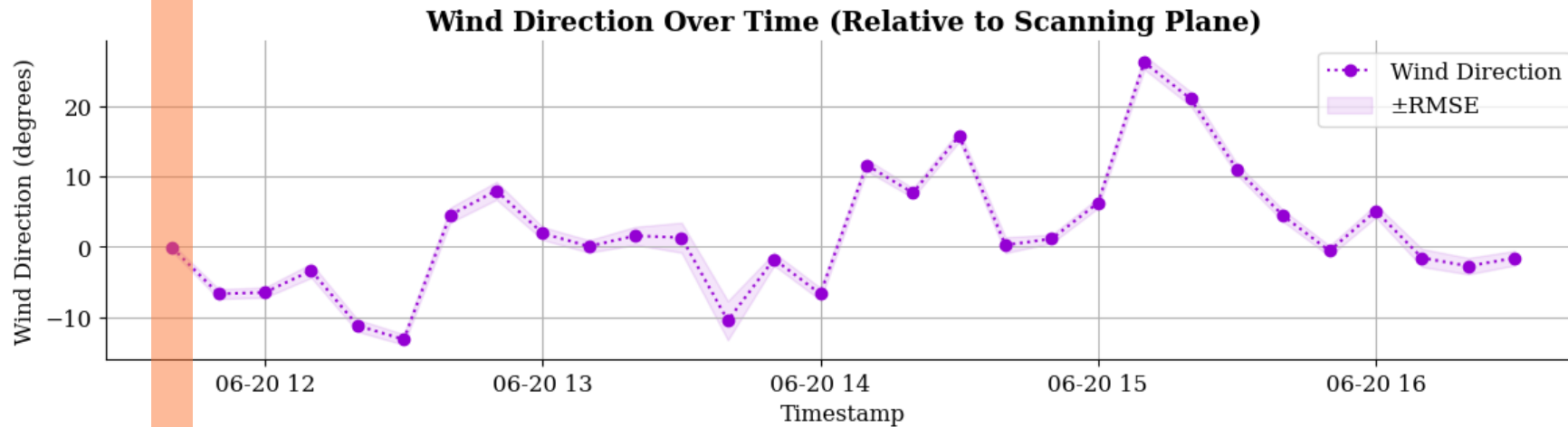
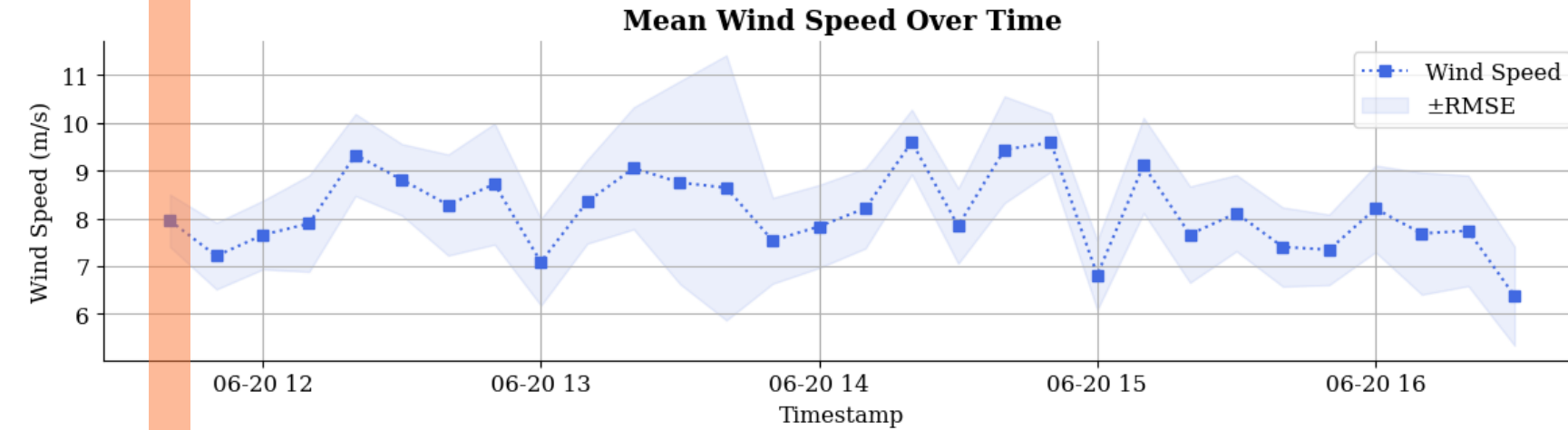


Solid moving target



# Wind Conditions

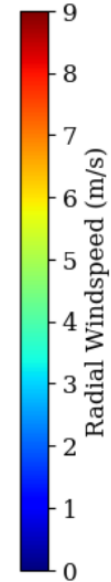
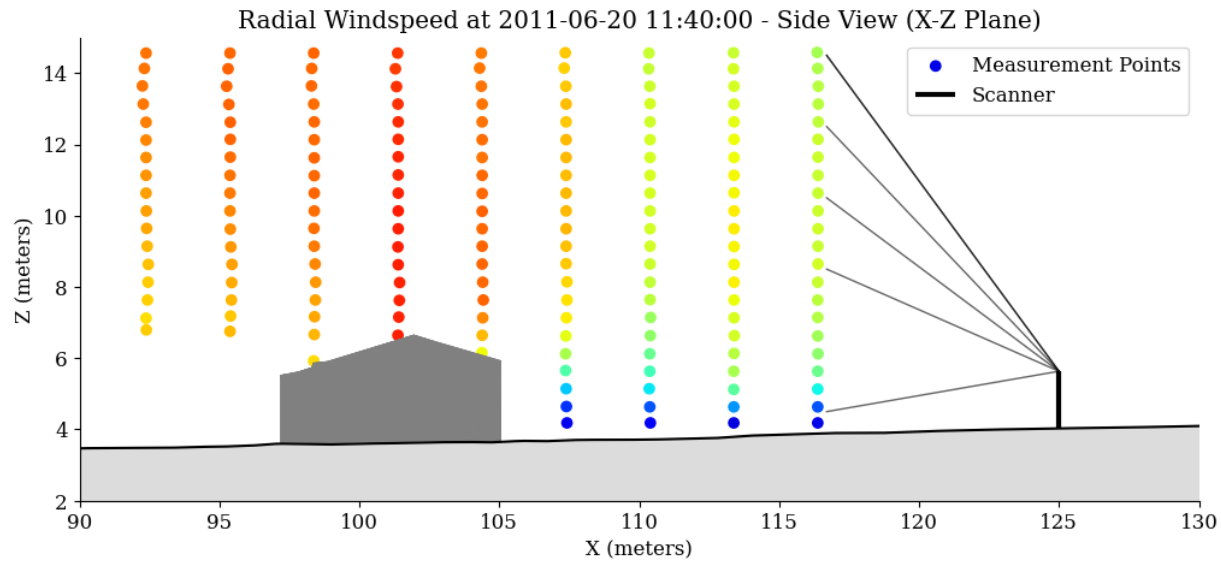
Time Interval: 2011-06-20 11:40 - 2011-06-20 16:30



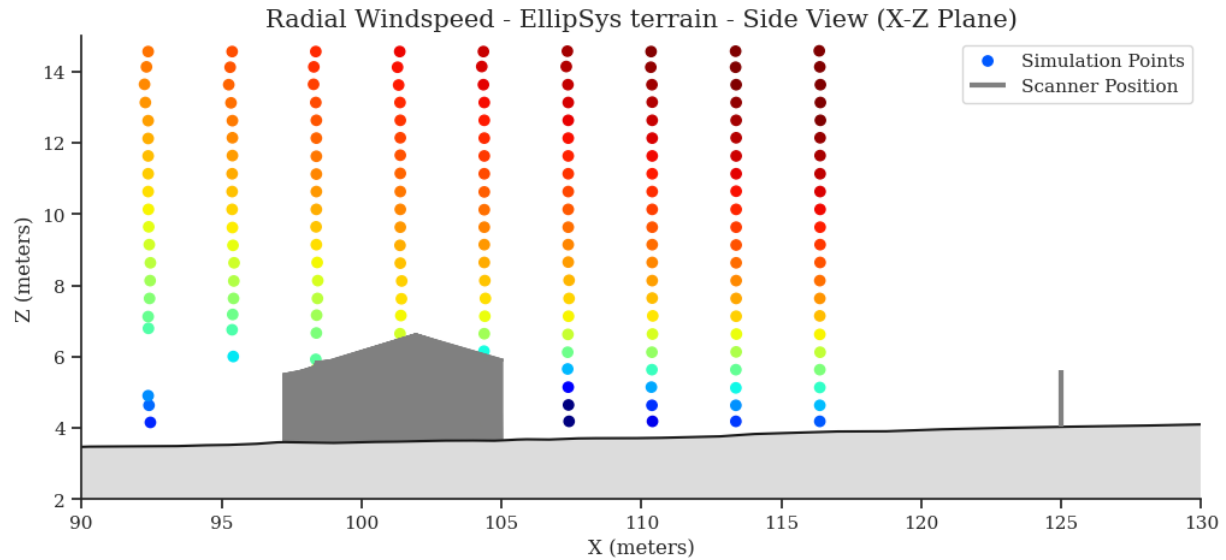
X: 40.08 m, Z: 8.93 m, Elevation Angle: 12.0°

# Comparison of Radial Windspeeds

Wind Scanner

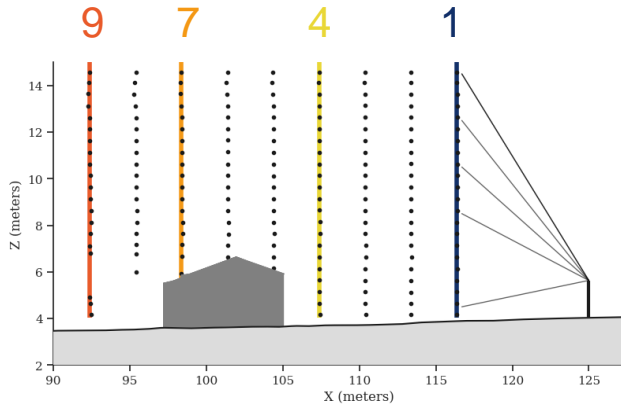


RANS Simulation

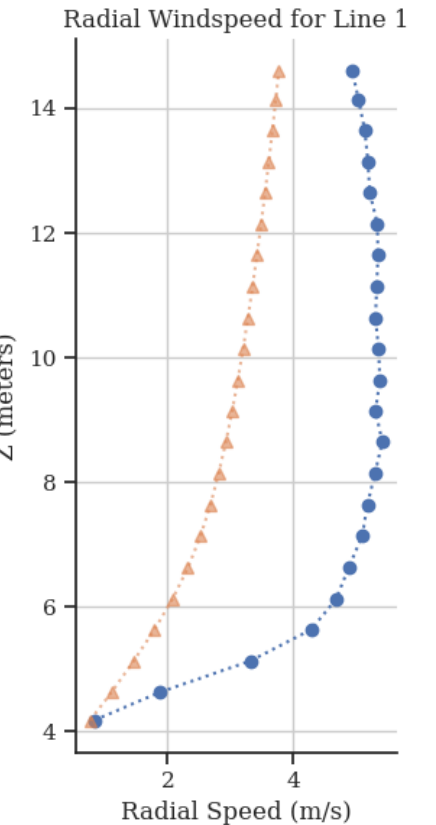
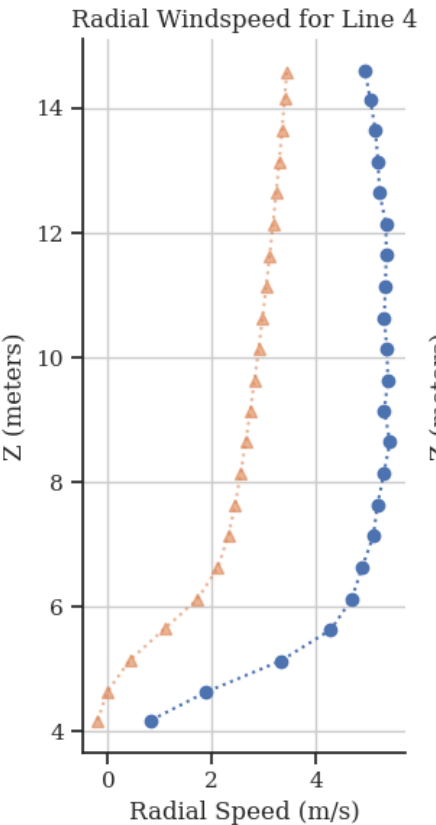
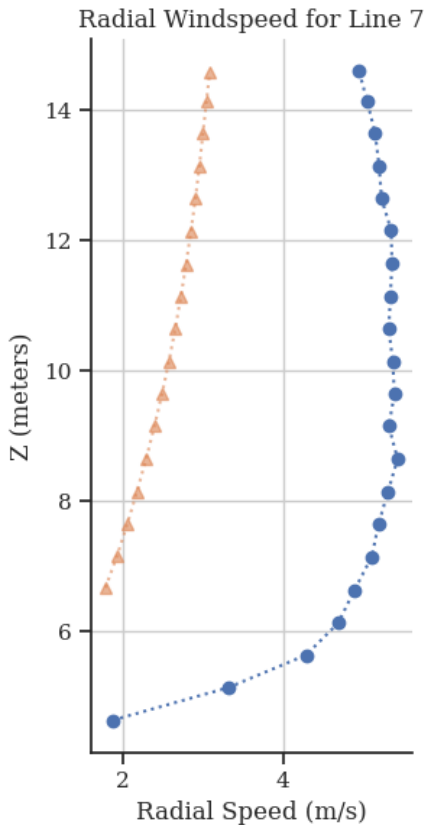
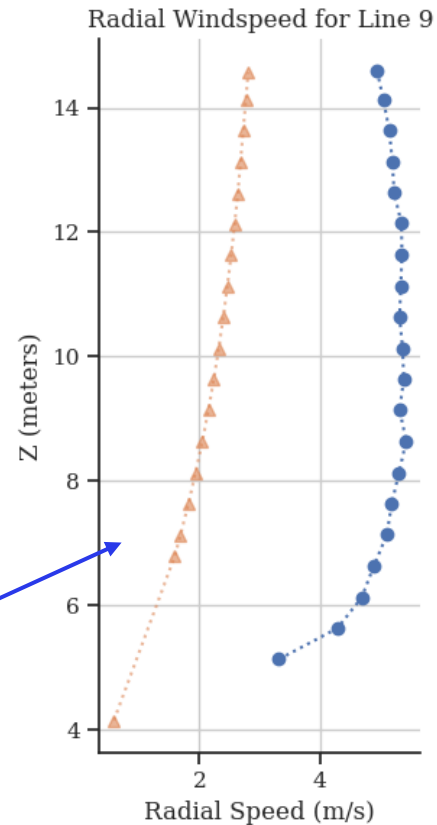




# First comparison of Wind profiles



Mismatch in inflow



● Windscanner (2011-06-20 11:40:00)    ▲ Simulation

# Conclusion & Outlook

- Rapid technological development of airborne lidar technology has led to radically improved accuracy and realism in 3D digital surface models of urban areas
- Make real and model worlds match: Achieve this with detailed building reconstruction and high-resolution Wind Scanner data

**Take-home Message:** Our work shows new possibilities in accurately modeling urban environments, which is crucial for various applications of local scale dispersion and flow modeling.

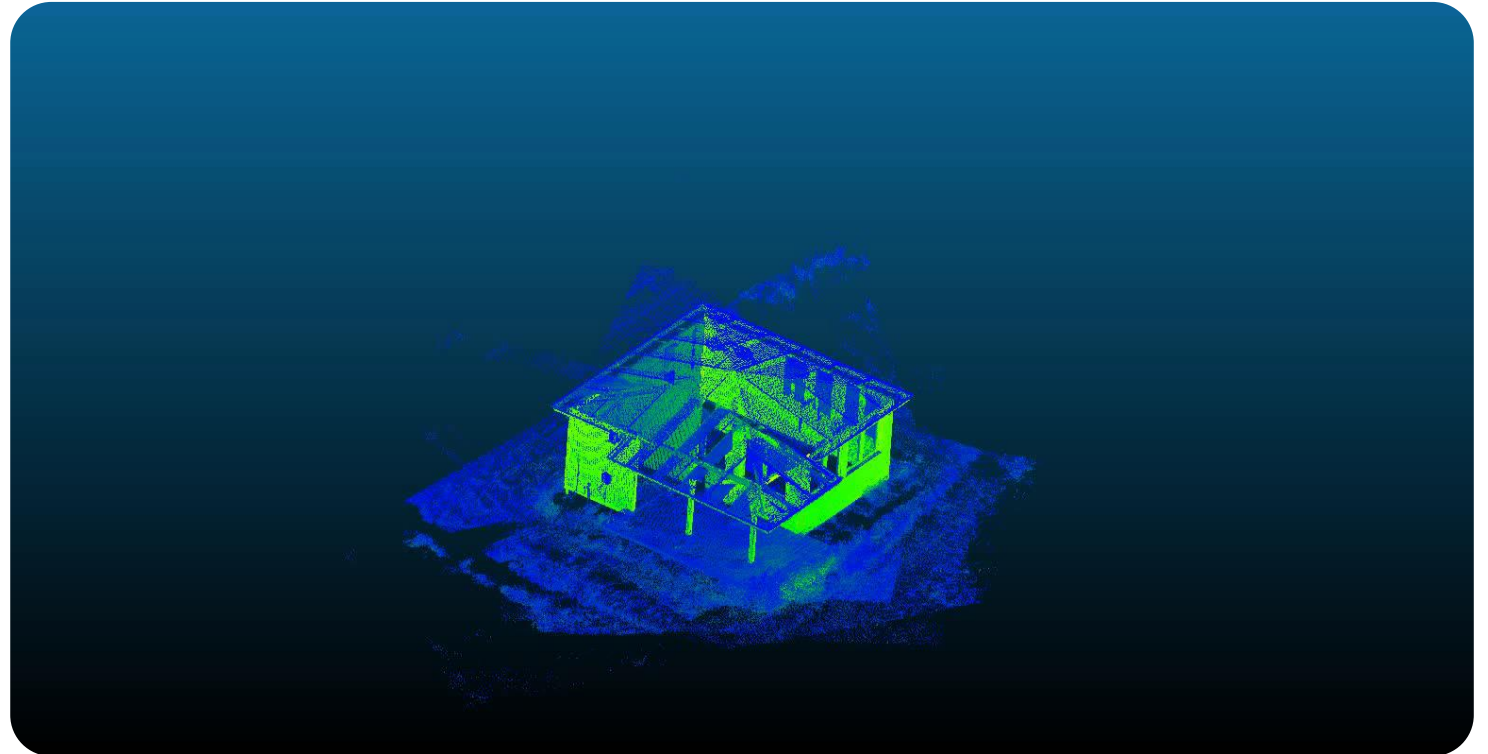
## Future Work:

- Matching inflow conditions for better comparative analysis
- Further processing of Wind Scanner data to compare Turbulent Kinetic Energy (TKE)
- Conducting a tracer experiment to validate our CFD dispersion simulation 😊



# Thank you for your attention!

Further Questions?  
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DTU



# References

- R. Peters, B. Dukai, S. Vitalis, J. van Liempt, and J. Stoter. (2022). Automated 3D Reconstruction of LoD2 and LoD1 Models for All 10 Million Buildings of the Netherlands. *Photogrammetric Engineering and Remote Sensing*, 88(3), 165–170..
- Troldborg, N., Sørensen, N. N., & Zahle, F. (2022). Immersed boundary method for the incompressible Reynolds Averaged Navier–Stokes equations. *Computers and Fluids*, 237, [105340]. <https://doi.org/10.1016/j.compfluid.2022.105340>