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# A baseline for source reconstruction using the inverse atmospheric modelling tool *FREAR*

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# Forensic Radionuclide Event Analysis and Reconstruction - the "FREAR" code

- Initially developed with the purpose of CTBT verification

- Required input:

(1) source-receptor sensitivities ( $M$ )

(2) observed airborne activity concentrations ( $y$ )

(Can deal with both detections and instrumental non-detections; it takes into account the possibility for misses and false alarms)

- FREAR can solve the inverse modelling problem using **two independent methods**: a cost function optimization method and a Bayesian MCMC method
- Users can **select the most appropriate source parameterization** for a given problem (such as multiple release segments or a release from a fixed location), and can add their custom source parameterization if needed
- The Bayesian inference approach provides an estimate on the uncertainties in a natural way. Furthermore, an ensemble of atmospheric transport modelling can be used to better **estimate model uncertainty**
- Code written in R, available on [GitLab](#) under GPLv3

# FREAR challenges and outlook

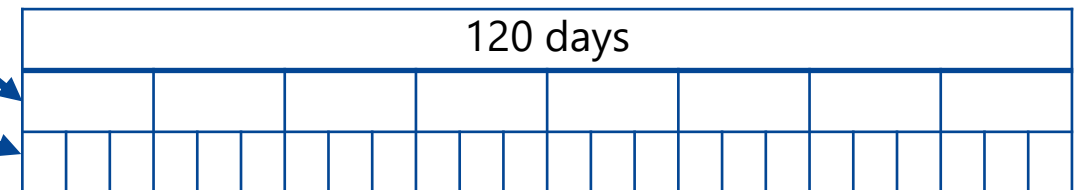
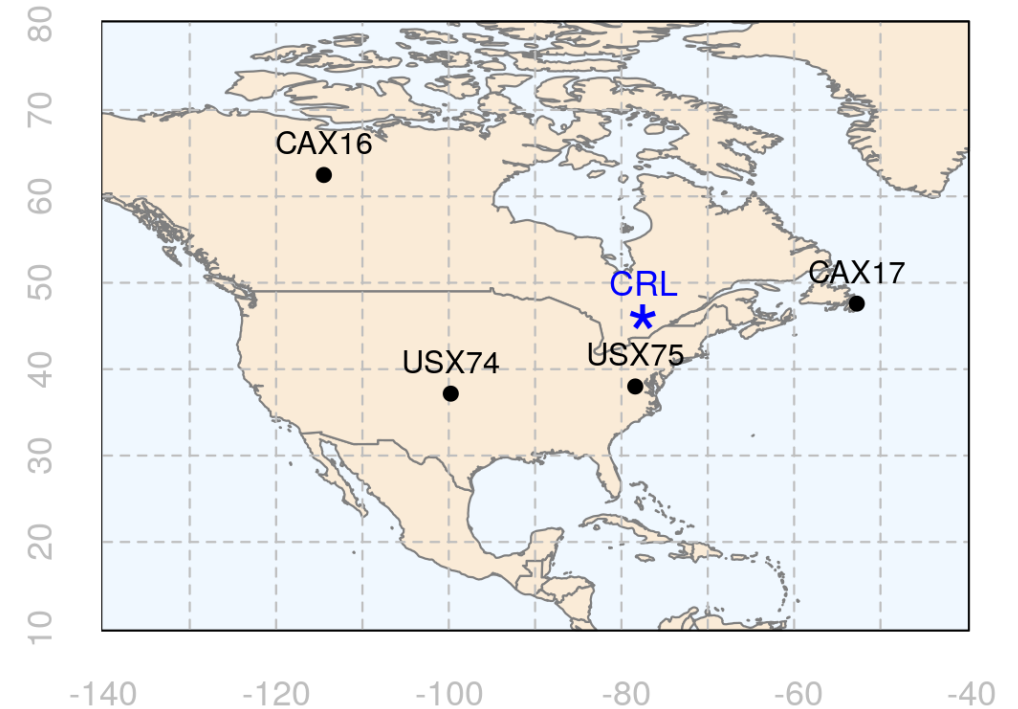
Some challenges:

- How to include different sources of observations (such as gamma dose rate measurements and deposition measurements)?
- FREAR performed well when applied to previous case studies; will it perform well when applied to the next case?
- ...
- Inclusion of deposition measurements → talk Stijn Van Leuven
- Apply FREAR over a set of test cases → [this talk](#)

**Purpose:** to establish a baseline for source reconstruction to facilitate testing of data, methods and settings

# Constructing a set of cases

- $^{133}\text{Xe}$  observations at four monitoring stations for the period 1 September 2014 – 30 December 2014 (120 d)
- Detections are linked with emissions from a (former) medical isotope production facility Chalk River Laboratories (CRL)
- Can we reconstruct the (known) source location of CRL?
- Two sets of case studies:
  - i. 8 cases with 15 d of observations
  - ii. 24 cases with 5 d of observations

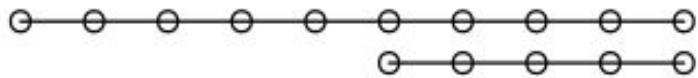


# ATDM and FREAR setup

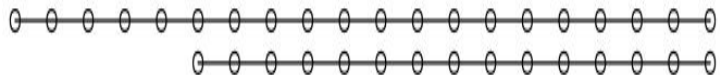
ECMWF input: 3-hourly at  $0.5^\circ \times 0.5^\circ$  for full NH

Flexpart output: daily at  $0.5^\circ \times 0.5^\circ$ , 0 – 100 m, full NH

5-day cases: 10 daily release segments



15-day cases: 20 daily release segments



## FREAR

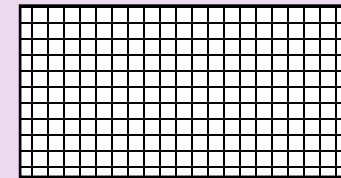
### Bayesian inference

- infer source term
- infer source location
- $\mathbf{y} = \mathbf{M} \mathbf{x}$



### Cost function

- optimize source term
- for each grid box
- $\mathbf{y} = \mathbf{M} \mathbf{x}$



### maximum-in-time PSR using Pearson / Spearman correlation

- for each grid box
- correlation between  $\mathbf{y}$  and  $\mathbf{M}$

### Accumulated-in-time FOR

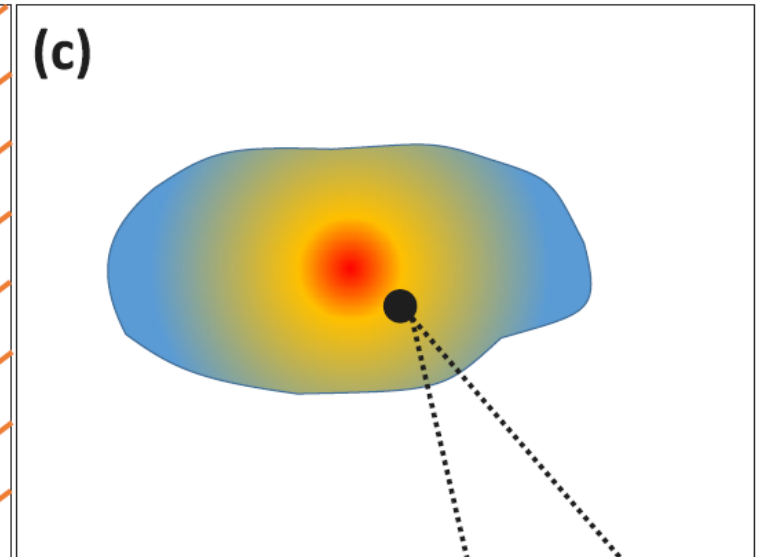
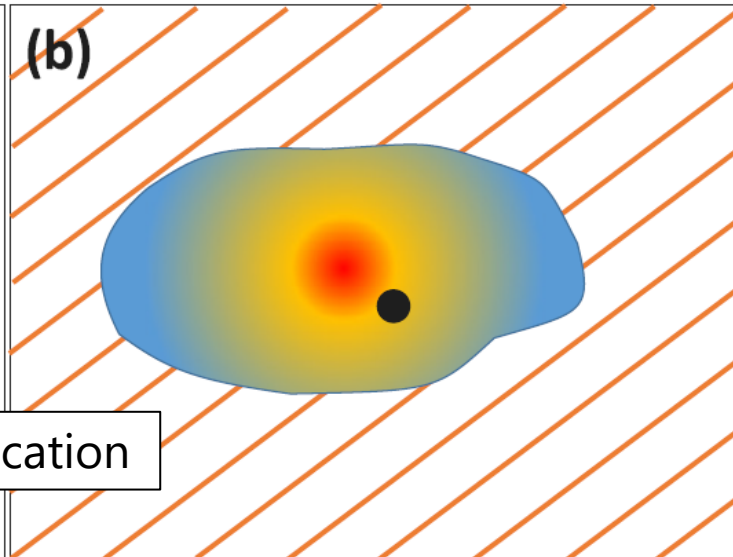
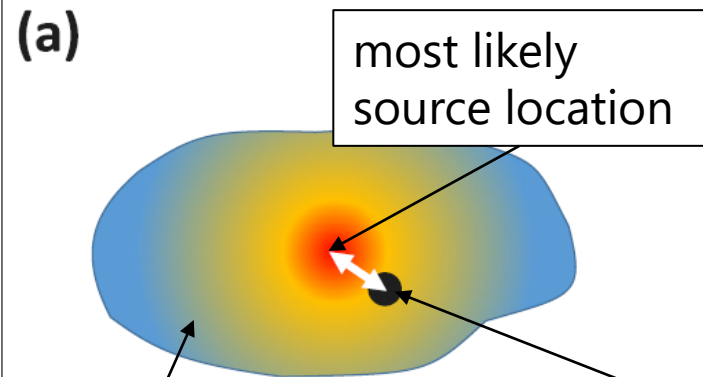
- for each grid box
- area where  $\mathbf{M}[\mathbf{y} > \mathbf{0}] > 0$  for any time

# Three verification metrics for source localisation

Distance  $[0, \infty]$

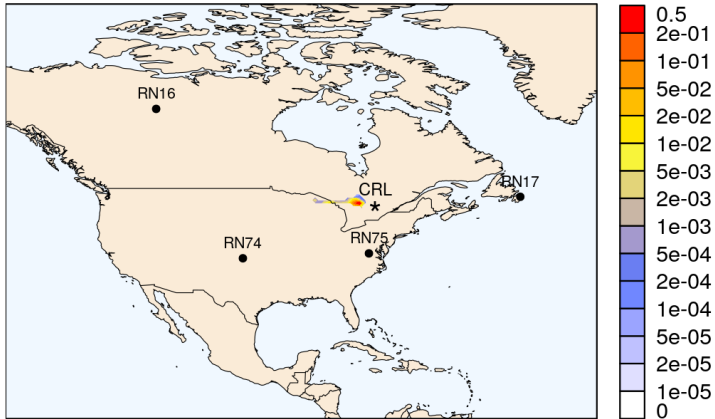
Fraction of domain excluded (FDE)  $[0, 1[$

Cumulative distribution score (full or subdomain)  $[0, 1]$

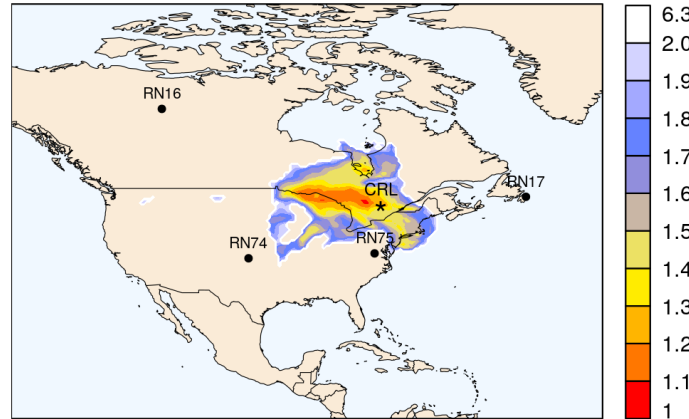


# Results: example of different inverse modelling methods and verification metrics

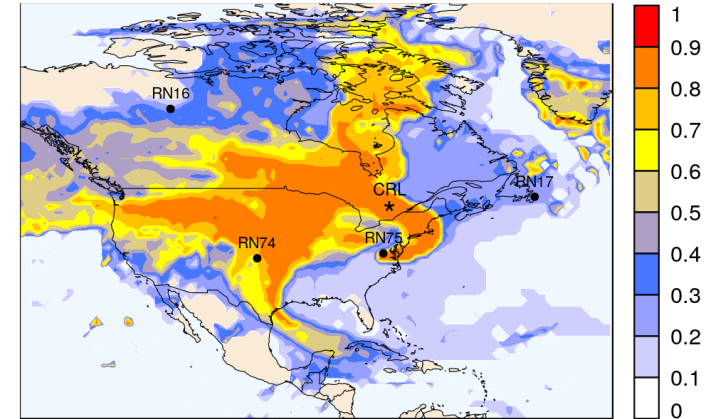
Bayesian source location probability



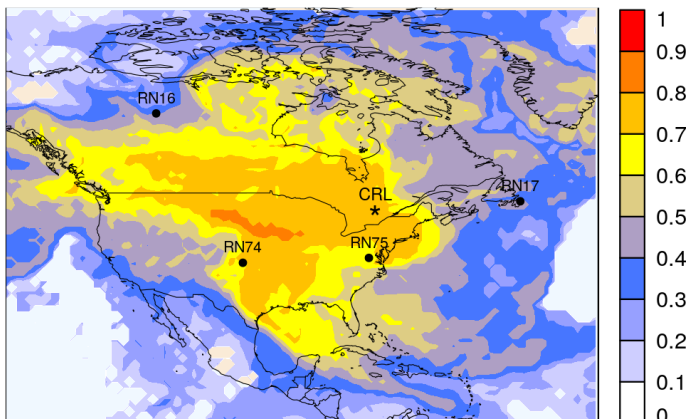
Residual cost after optimisation



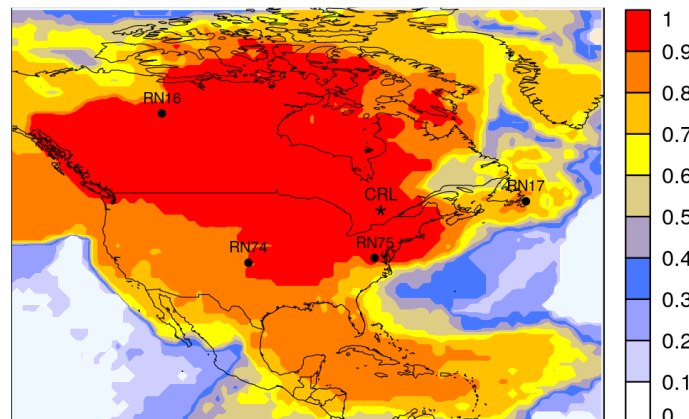
maximum-in-time PSR (Pearson)



maximum-in-time PSR (Spearman)

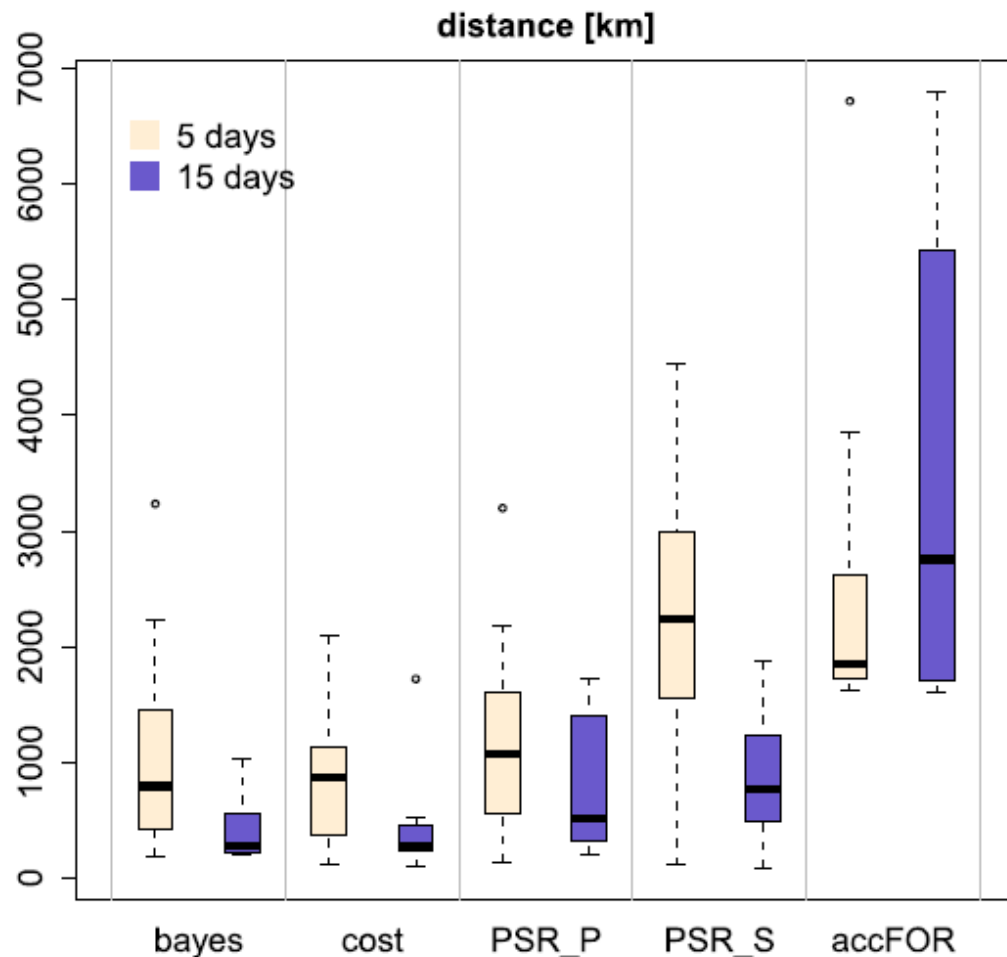


Fraction of overlapping SRS of detections



Method	Distance [km]	CDS	FDE
bayes	199	0.000	0.998
cost	226	0.884	0.949
corr (P)	2274	0.979	0.355
corr (S)	1494	0.942	0.091
FOR	1685	0.928	0.252

# Results: comparing different methods for 5 days and 15 days of observations (1/2)



## Comparing methods:

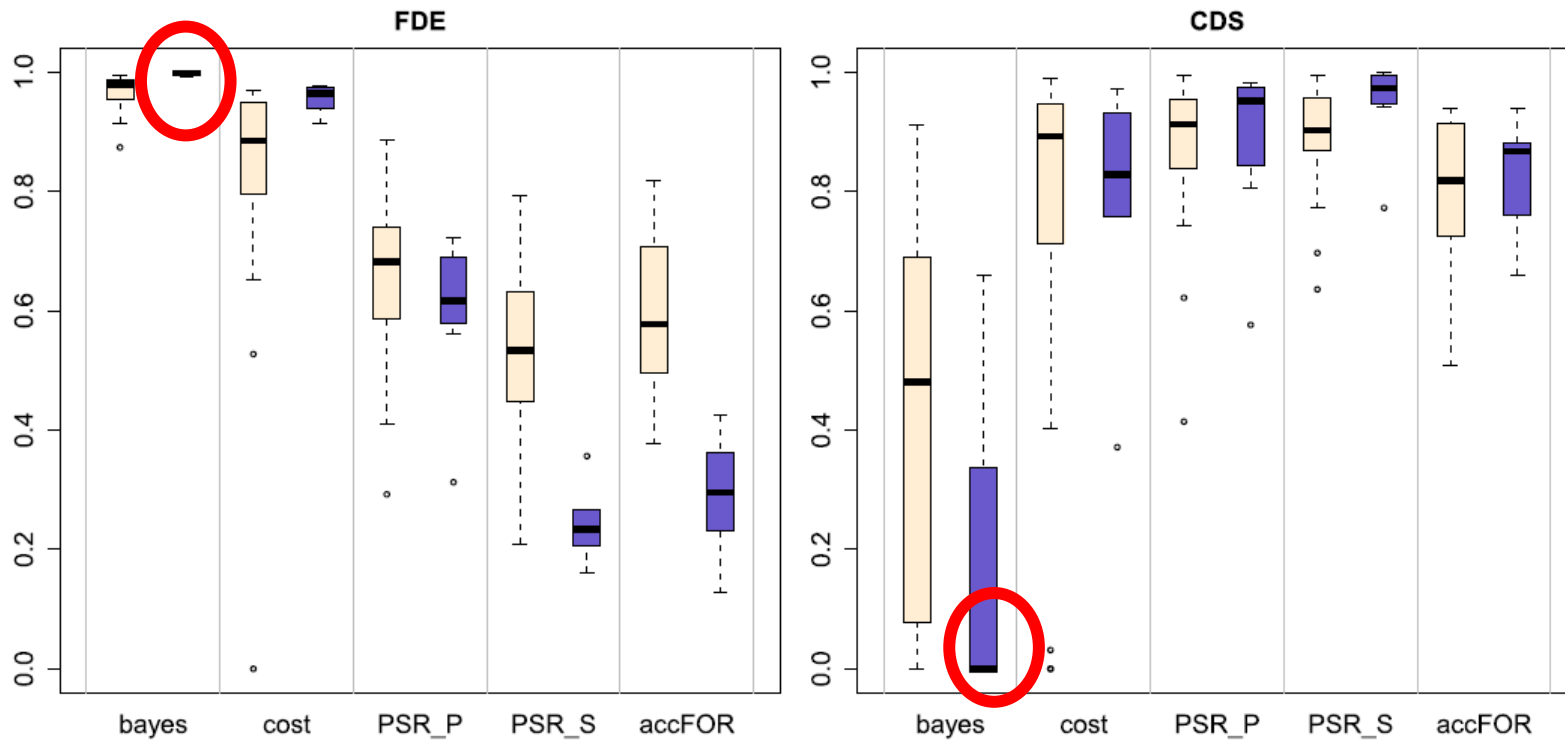
- *bayes* and *cost* are able to locate the source much better than other methods

## Comparing 5 d vs 15 d observations:

- *bayes* and *cost* show a significant improvement (from 800 km to 270 km)



# Results: comparing different methods for 5 days and 15 days of observations (2/2)



## Comparing methods:

- *bayes*: poor CDS score, other methods comparable
- *bayes* and *cost*: exclude large fraction of search domain

## Comparing 5 d vs 15 d observations:

- *bayes* and *cost* show a deterioration in CDS score and an improvement in the fraction of domain excluded
- other methods show an improvement in the CDS score and a deterioration in the fraction of domain excluded

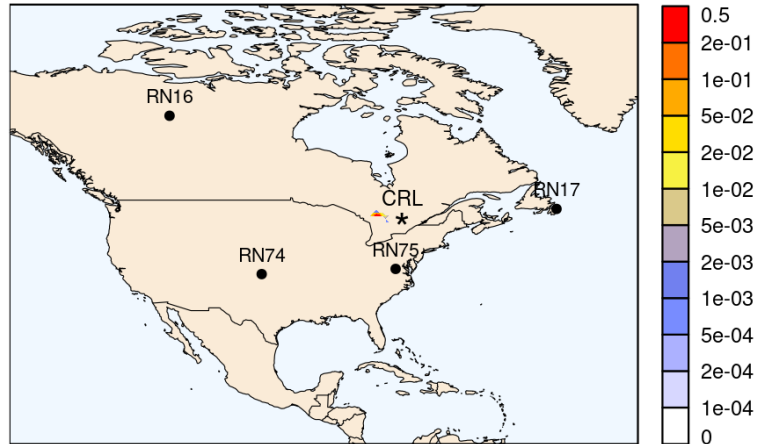
**bayes at times overconfident as a very large fraction of the domain is excluded and the true source location has zero probability**

# Increasing uncertainty in the Bayesian inference: introducing multipliers (1/2)

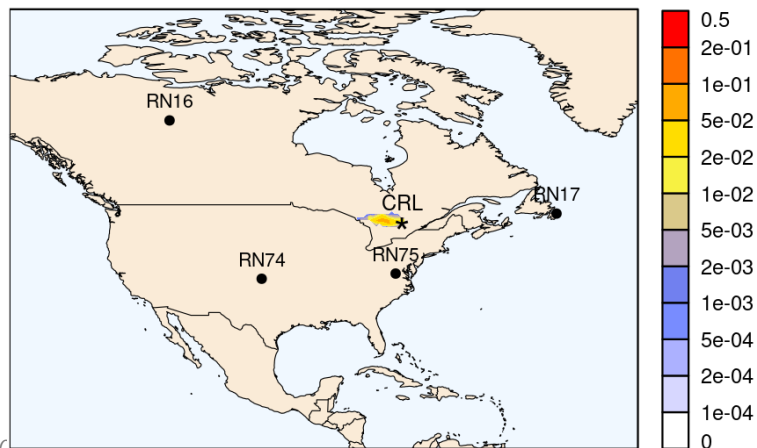
Default	Multipliers
normal likelihood	~
elaborate model for non-detections, false alarms, misses	~
uncertainty sigma is replaced by a heavy-tail distribution	~
one relative uncertainty for all observations (s = 1)	~
	$y_i = m_i M_{ij} x_j + \varepsilon_i$ $m_i \in [0.1, 10]$ multipliers inferred

# Increasing uncertainty in the Bayesian inference: introducing multipliers (2/2)

Default ( $s = 1$ )



Using multipliers

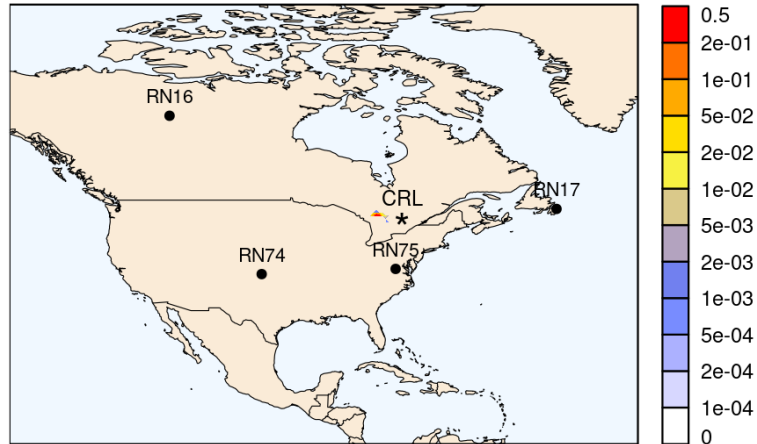


# Increasing uncertainty in the Bayesian inference: uncertainties inferred (1/2)

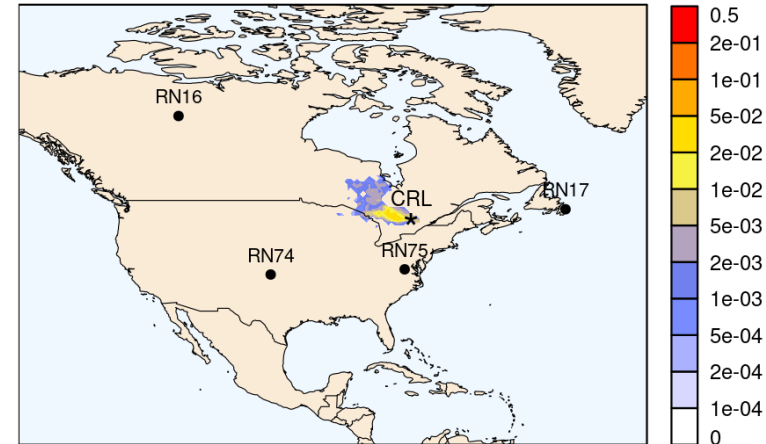
Default	Multipliers	Uncertainty inferred
normal likelihood	~	~
elaborate model for non-detections, false alarms, misses	~	simple model for dealing with non-detections
uncertainty sigma is replaced by a heavy-tail distribution	~	sigma is used
one relative uncertainty for all observations (s = 1)	~	one relative uncertainty for each station, inferred $\sigma \in [0.3, 10]$
	$y_i = m_i M_{ij} x_j + \varepsilon_i$ $m_i \in [0.1, 10]$ multipliers inferred	

# Increasing uncertainty in the Bayesian inference: uncertainties inferred (2/2)

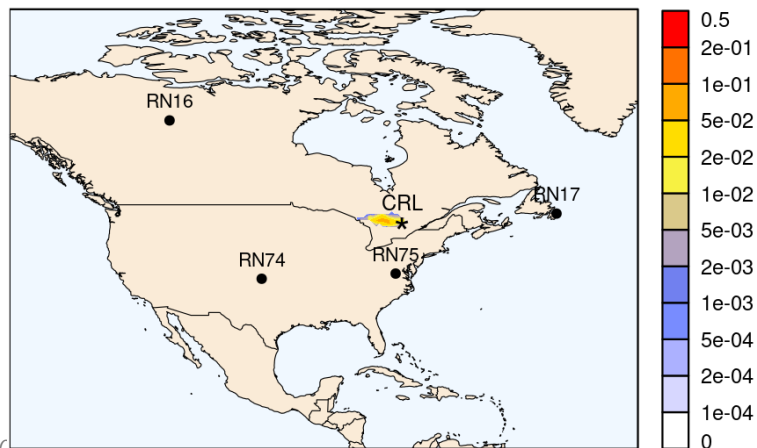
Default ( $s = 1$ )



Uncertainties inferred



Using multipliers

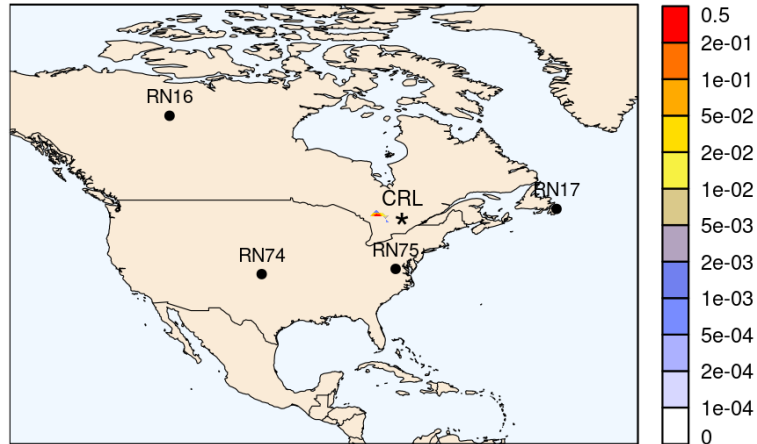


# Increasing uncertainty in the Bayesian inference: very high input uncertainty (1/2)

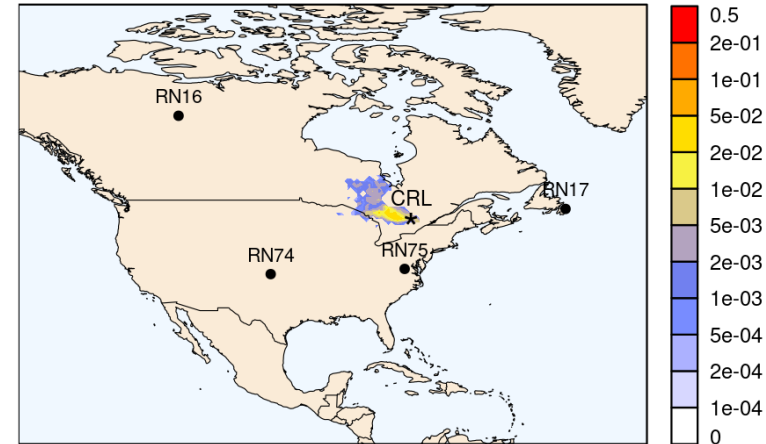
Default	Multipliers	Uncertainty inferred	Default with high s
normal likelihood	~	~	~
elaborate model for non-detections, false alarms, misses	~	simple model for dealing with non-detections	~
uncertainty sigma is replaced by a heavy-tail distribution	~	sigma is used	~
one relative uncertainty for all observations (s = 1)	~	one relative uncertainty for each station, inferred $\sigma \in [0.3, 10]$	s = 10
	$y_i = m_i M_{ij} x_j + \varepsilon_i$ $m_i \in [0.1, 10]$ multipliers inferred		

# Increasing uncertainty in the Bayesian inference: very high input uncertainty (2/2)

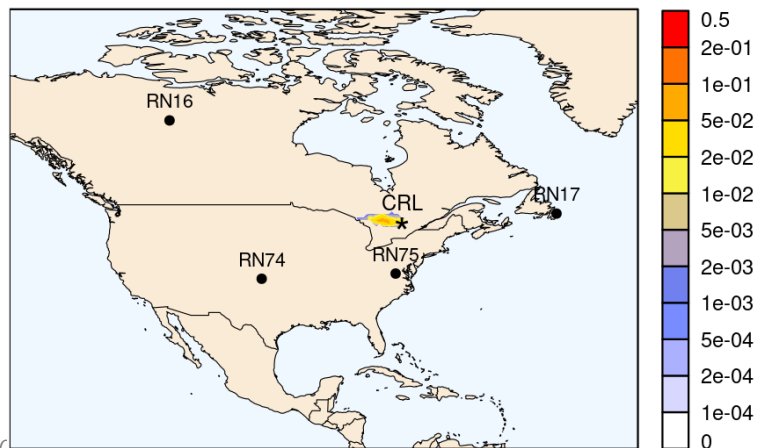
Default ( $s = 1$ )



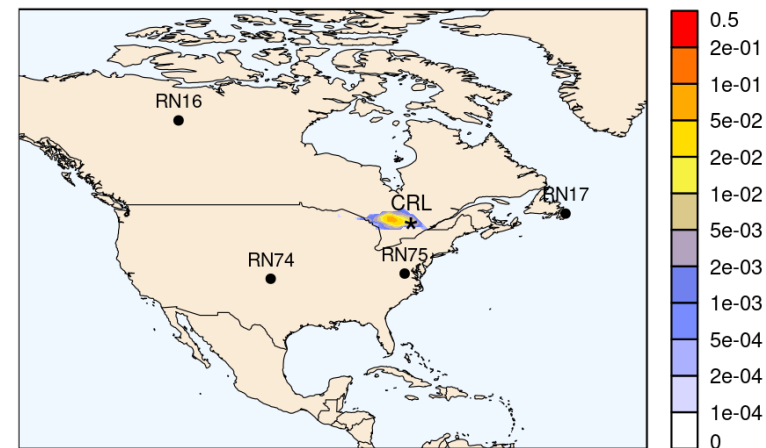
Uncertainties inferred



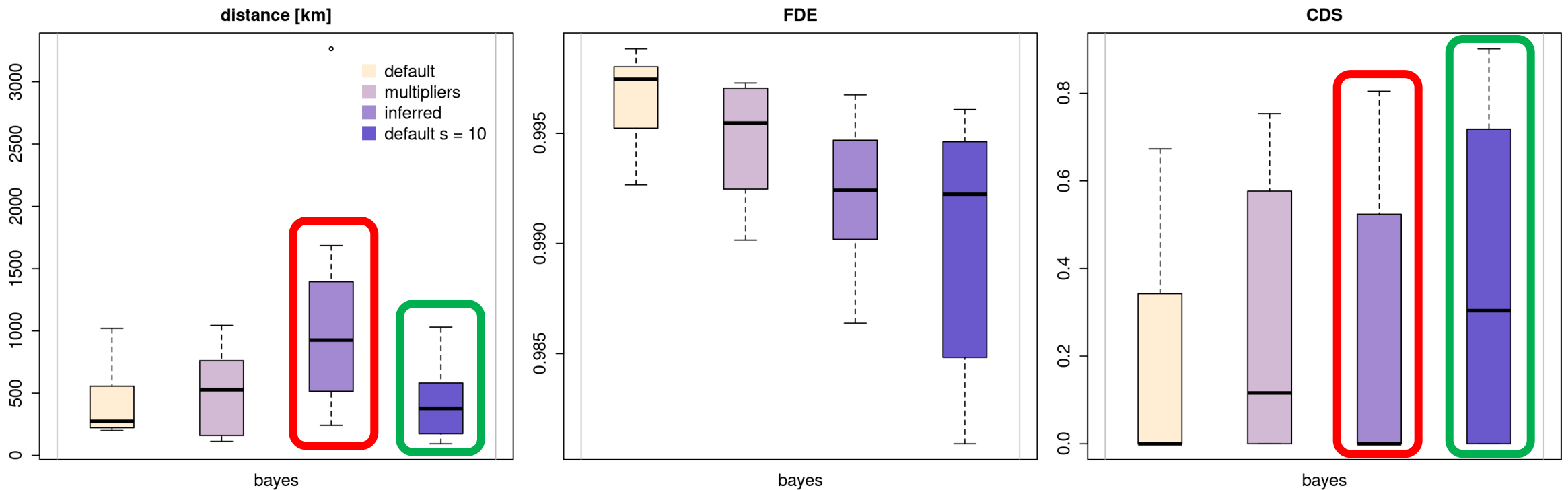
Using multipliers



Default ( $s = 10$ )



# All methods succeed in increasing the uncertainty in the selected case, but when applied to all cases...





# Summary and conclusions

Two sets of case studies have been defined for inverse modelling using  $^{133}\text{Xe}$  observations associated to a (former) medical isotope production facility Chalk River Laboratories:

- 8 cases using 15 days of observations and 24 cases using 5 days of observations

These sets allow for:

- a comparison of data (observation selection, NWP input, ATM input, ...)
- a comparison of methods (inverse modelling methods, source parameterizations, ...)
- the testing of new or modified inverse modelling algorithms

Findings:

- Bayesian inference and cost function optimization are able to exclude a large fraction of the location search domain, contrary to simpler methods
- Bayesian inference underestimates uncertainties since the true source location sometimes falls outside the possible source region (note: other methods do not optimize for source location)
- By considering several test cases, the best method can be selected

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