

Paper H15-154

# Revisiting 1992 HARMO1 (Riso) comments on limitations of short range atmospheric dispersion models

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- My paper at HARMO1 at Riso in 1992 gave a “confessional” of limitations of then state-of-the art models (e.g., OML, ADMS, HPDM)
- Have these limitations been resolved?
- Are there additional new limitations?

# 1992 List of Limitations

- 1 Mixing depth
- 2 Vertical profiles of turbulence
- 3 Nocturnal jet
- 4 Non-steady-state periods
- 5 Surface constants ( e.g., albedo,  $z_0$ )
- 6 Surface energy balance parameters
- 7 Lagrangian time scales

# 2013 Additional Limitations

8 Low wind stable

9 Steep terrain, bldg obstacles,  
land-use variations

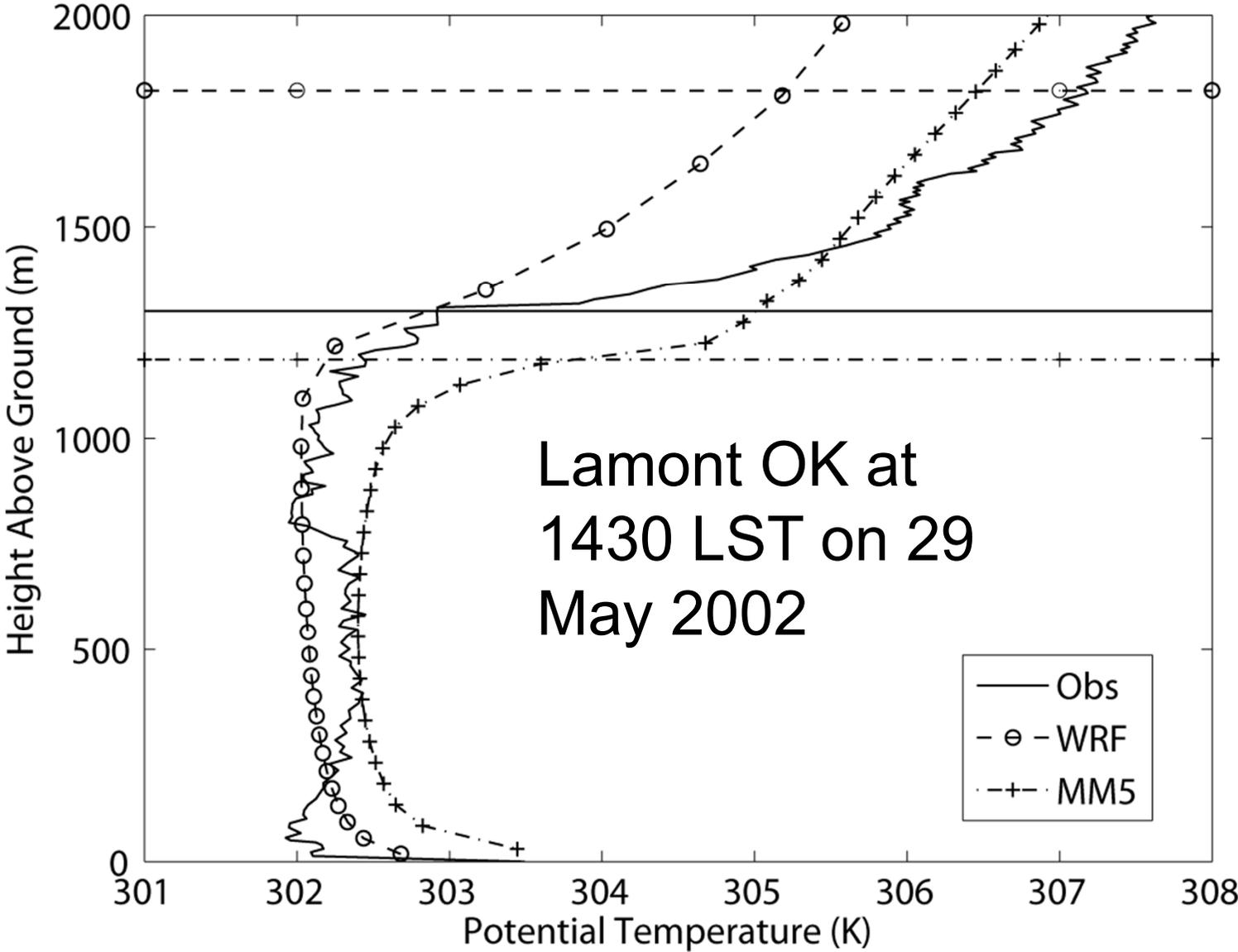
10 Is new technology helping?

11 Dense plumes and chemical  
reactions

# 1. Mixing depth $z_i$

- Models look for mixing depth  $z_i$  for each hour, but 30 or 40 % or more of the time  $z_i$  is “fuzzy”
- We still desire routine observations of vertical structure ( $u$ ,  $T$ , turb) by remote sounders through the entire boundary layer ( $1 \text{ m} < z < 3000 \text{ m}$ )
- Erroneous  $z_i$  are often found to be the cause of large over or underpredictions of concentration  $C$

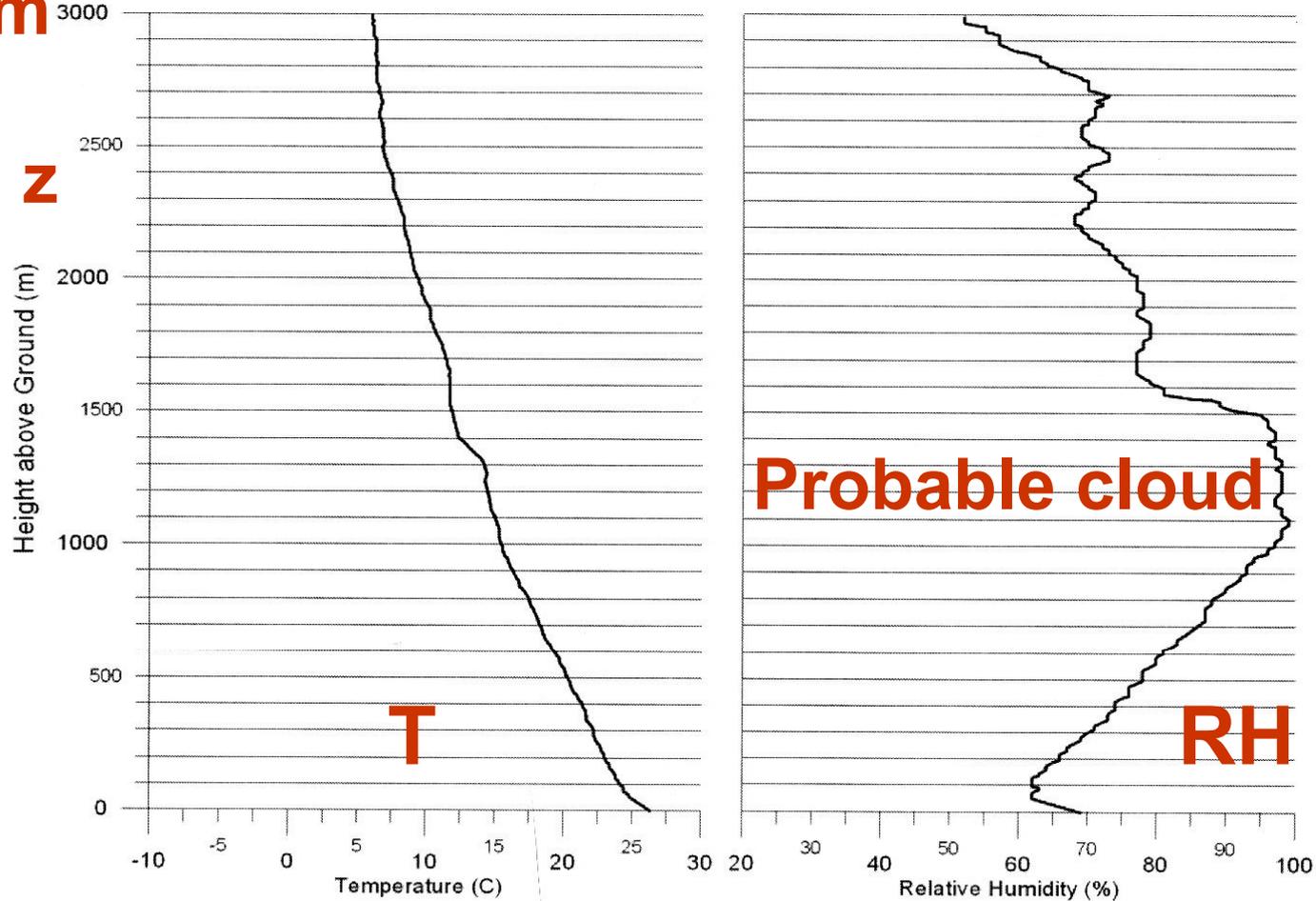
# Radiosonde profile with obvious $z_i$



# Example of observed T and RH profile with vague mixing depth

Balloon-Borne Sounding  
Location 4 Morris, OK (Lat = 35.69, Lon = -95.86)  
May 29, 2002 20:30 UTC

3000 m



## 2. Vertical profiles of turbulence ( $\sigma_v$ and $\sigma_w$ )

- Best to use observations (if accurate) with remote sounders but not widely available and do not cover all times and the entire depth of interest
- Models used Monin-Obukhov Similarity Theory (MOST) profile formulas for turbulence inputs to models. Uncertainties at top of PBL and during stable conditions, especially with low winds
- Minimum  $\sigma_v$  and  $\sigma_w$  are prescribed based on obs
- Mesoscale met models can provide these but much uncertainty

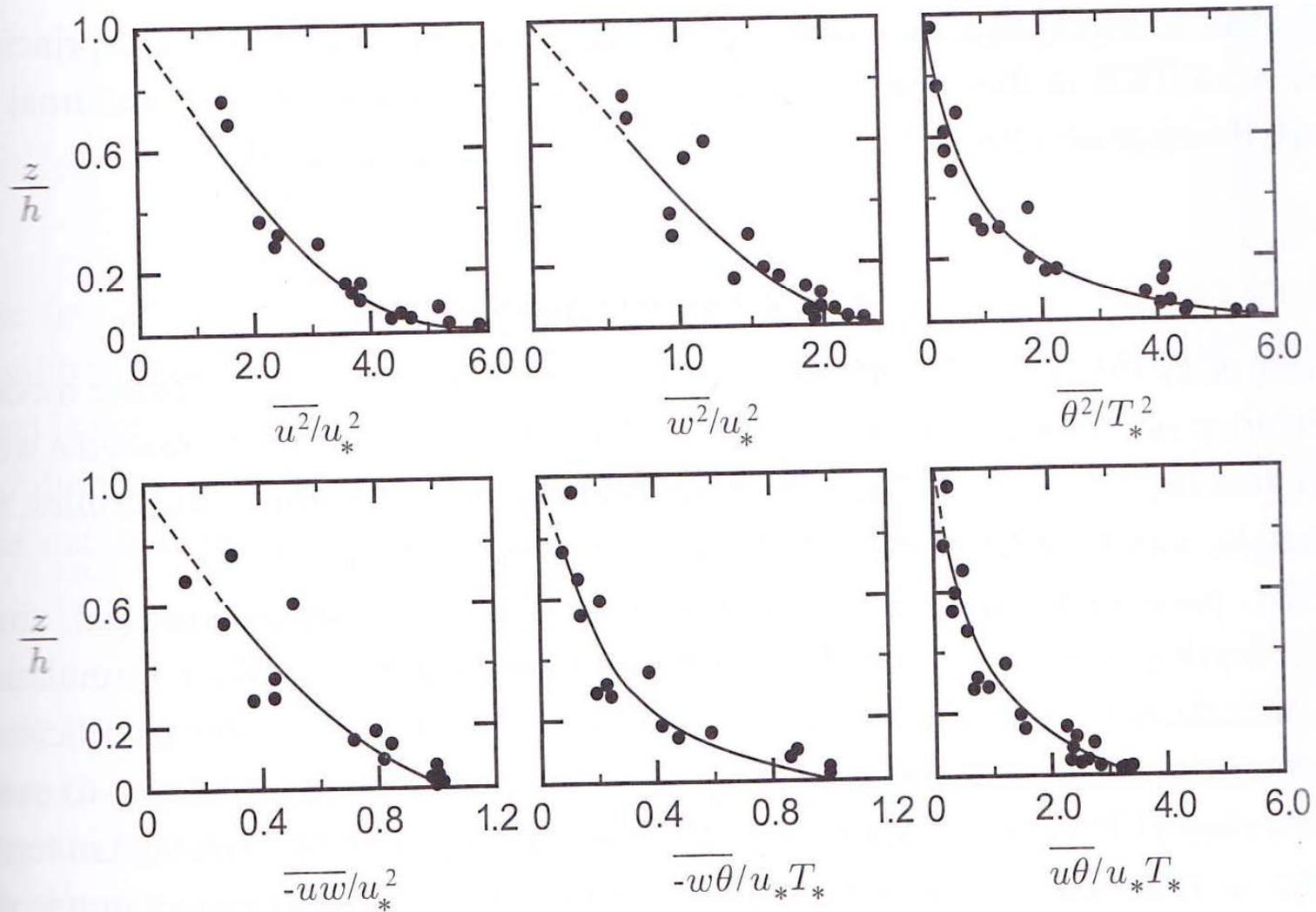


Figure 12.8 Vertical profiles of dimensionless variances and covariances measured in the early-evening Minnesota runs shown in Figure 12.2. The SBL depth  $h$  ranged from 30 m to 400 m over the seven runs. The curves are visual fits to the data. From Caughey *et al.* (1979).

**From Wyngaard 2010**

### 3. Nocturnal jet

- Was major concern in 1992; could influence tall stack plumes and carry them 100 km in 1 or 2 hrs
- Also leads to pulsing nighttime BL with turbulent bursts to ground (depends on critical  $Ri$ )
- Has mostly dropped off “radar screen” but still of concern.

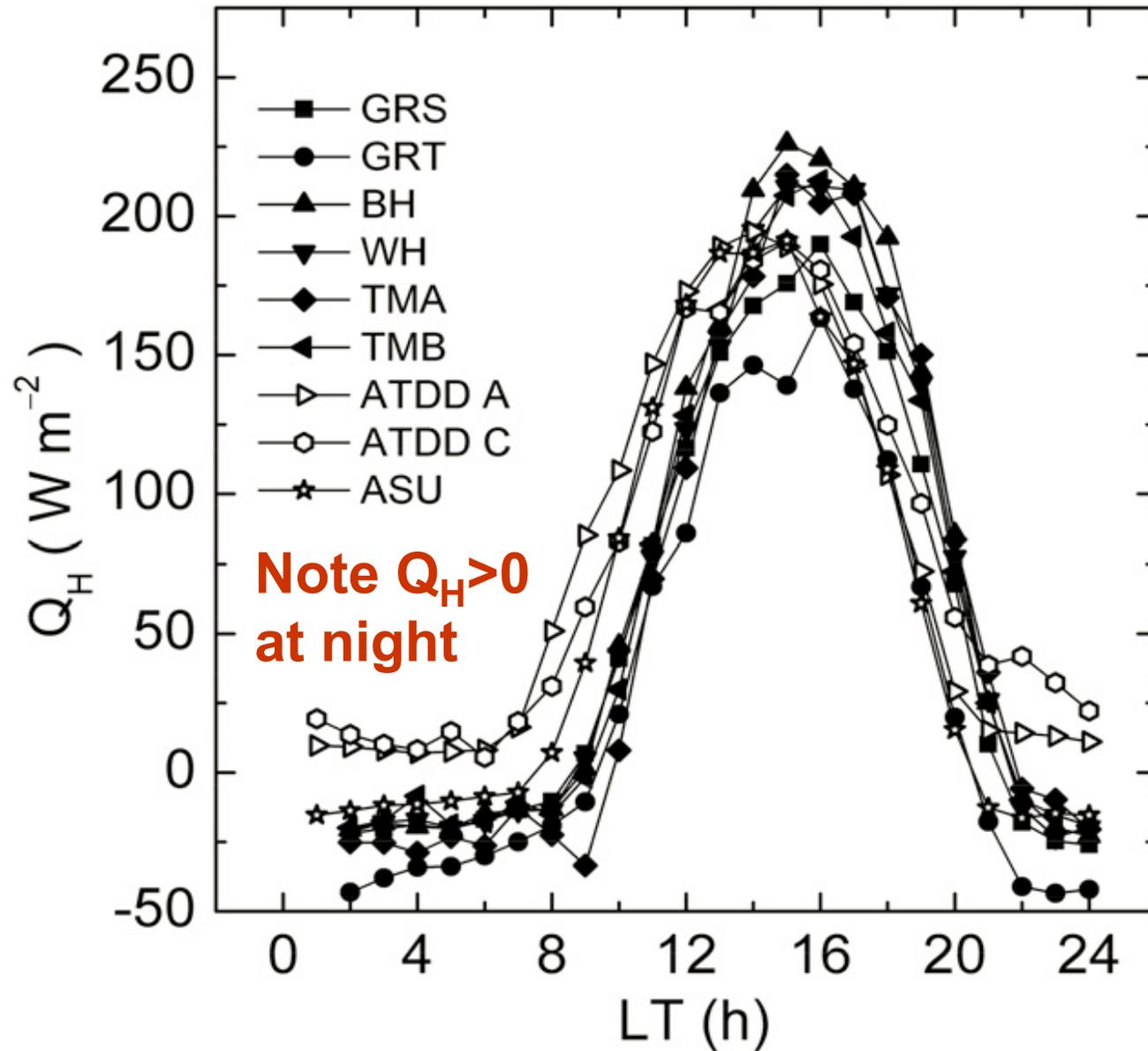
## 4. Non-steady-state periods

- Weather often changes from hour to hour.
- Straight-line Gaussian plume models assume constant PBL profiles exist over 50-80 km downwind distance. But plume may only travel 5 km in an hour.
- Still a problem. In the USEPA, AERMOD is assumed to be valid to 50 km for a given one-hr run.
- Could switch to a segmented plume model. Or a Lagrangian Puff or Particle model (e.g., CALPUFF in US)

## 5. Surface constants (e.g., albedo, $z_0$ ) and 6. Surface energy balance

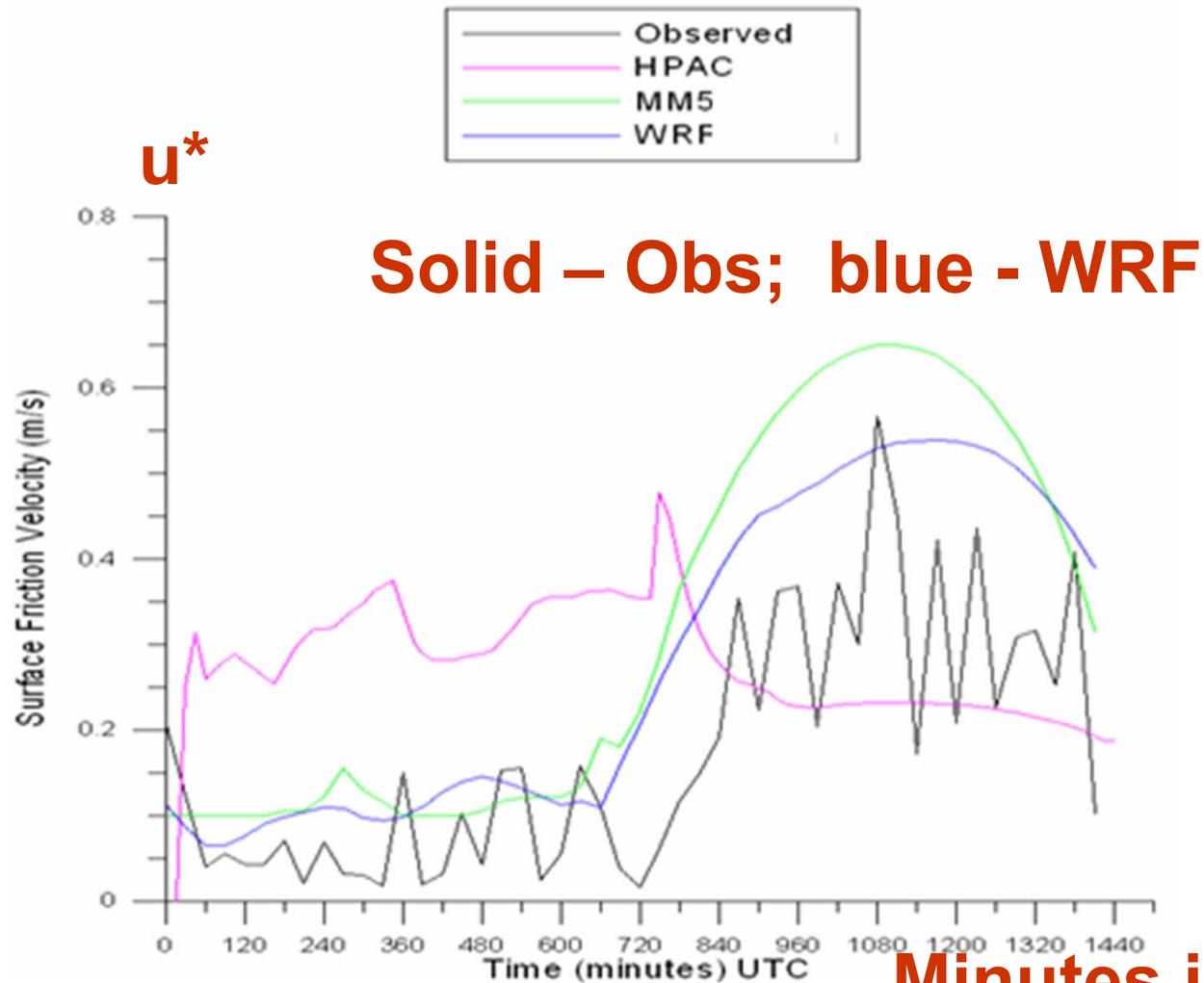
- 1992 models used parameterizations from Van Ulden, Holtslag et al.
- Much progress by climate modelers who want to know surface fluxes to an accuracy of a few %.
- Surface constants and energy balances have been well-studied in urban and rural areas as part of local climatology and chemical flux field programs.
- Yet I notice that not many of these advances by the climate modelers have made their way into the short-range dispersion models.

# Observed diurnal sensible heat flux $Q_H$ at built up (open symbols) and suburban sites in Oklahoma City



# Could use Met models (e.g. WRF) for $u^*$ and other met variables, but ...

Comparison to Central Facility Sonic Anemometer at 60m  
Location 1 Lamont, OK (Lat= 36.61, Lon= -97.49)  
May 29, 2002 30 minute average



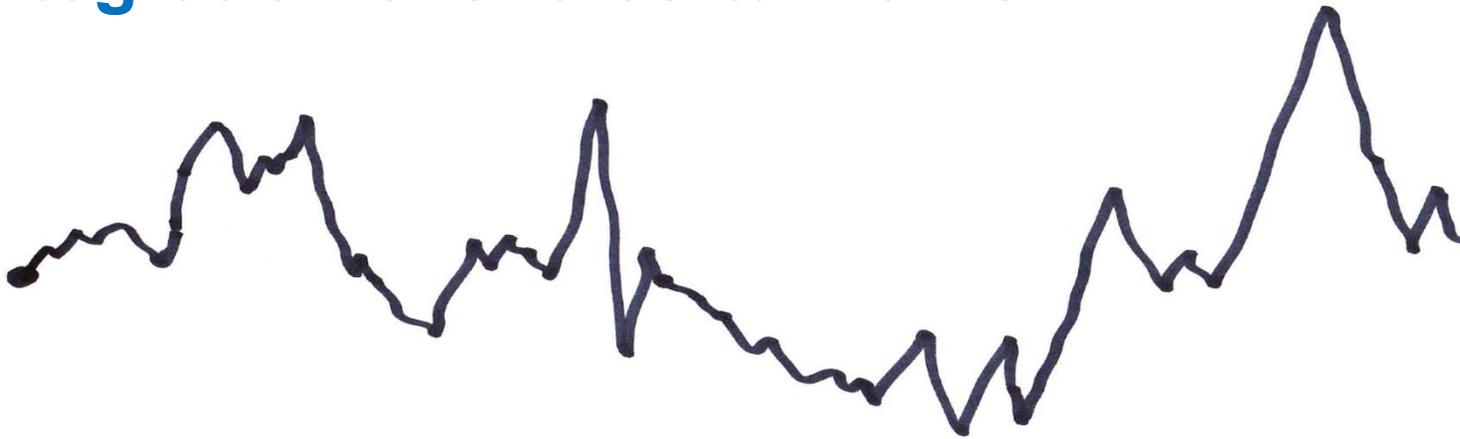
Minutes in 29 May

## 7. Lagrangian time scales $T_L$

- Most models now use an estimate of  $T_L$  (for y and z components) to estimate dispersion.  $T_L$  is defined locally rather than applying to whole trajectory.
- Lagrangian particle dispersion models (LPDMs) are widely used except by the US EPA
- Studies since 1992 show that  $T_{Ly}$  is larger than thought.  $\sigma_y$  grows with linear t or x for many hours
- In urban areas,  $T_L$  is determined by street width rather than distance to nearest surface
- AERMOD switches to K model for vertical dispersion near ground where  $T_{Lz}$  approaches 0

# Lagrangian particle motion

Taylor, Pasquill etc defined  $T_L$  based on integration over a certain time

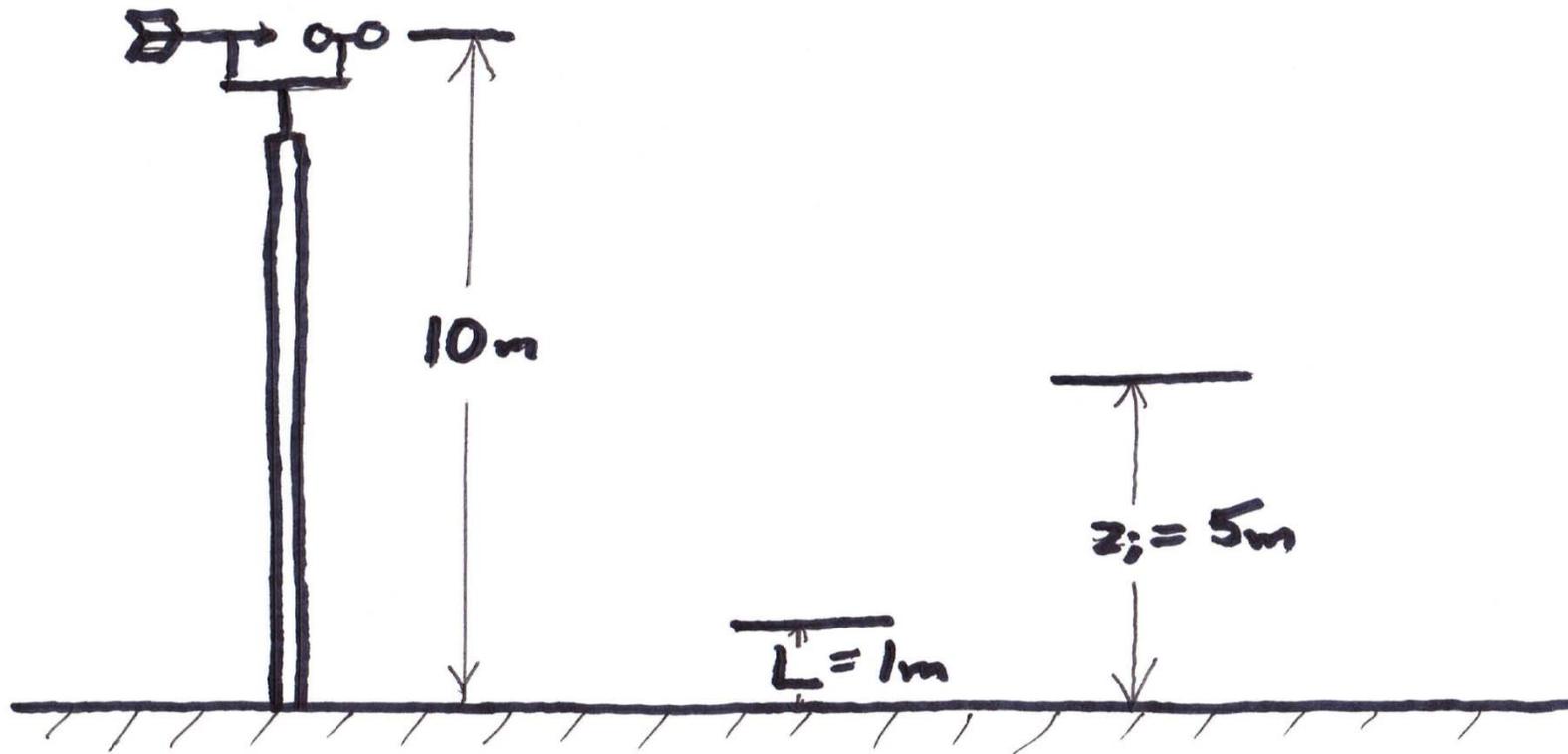


LPDMs often calculate particle movement based on local  $T_L$ .  $T_{Lz}$  varies considerably with height.

## New 8. Low wind stable

- Dispersion model over and under-predictions found
- MOST breaks down; light and variable winds
- $z$  of obs  $u$  may be above  $z_i$
- Models use empirical formulas for  $u^*/u$ , sensible heat flux  $H_s$ ,  $L$
- Current studies (e.g., Luhar) trying to fix this
- The two primary tracer experiments are from 1970s

# Low wind stable scenario with $L = 1$ m

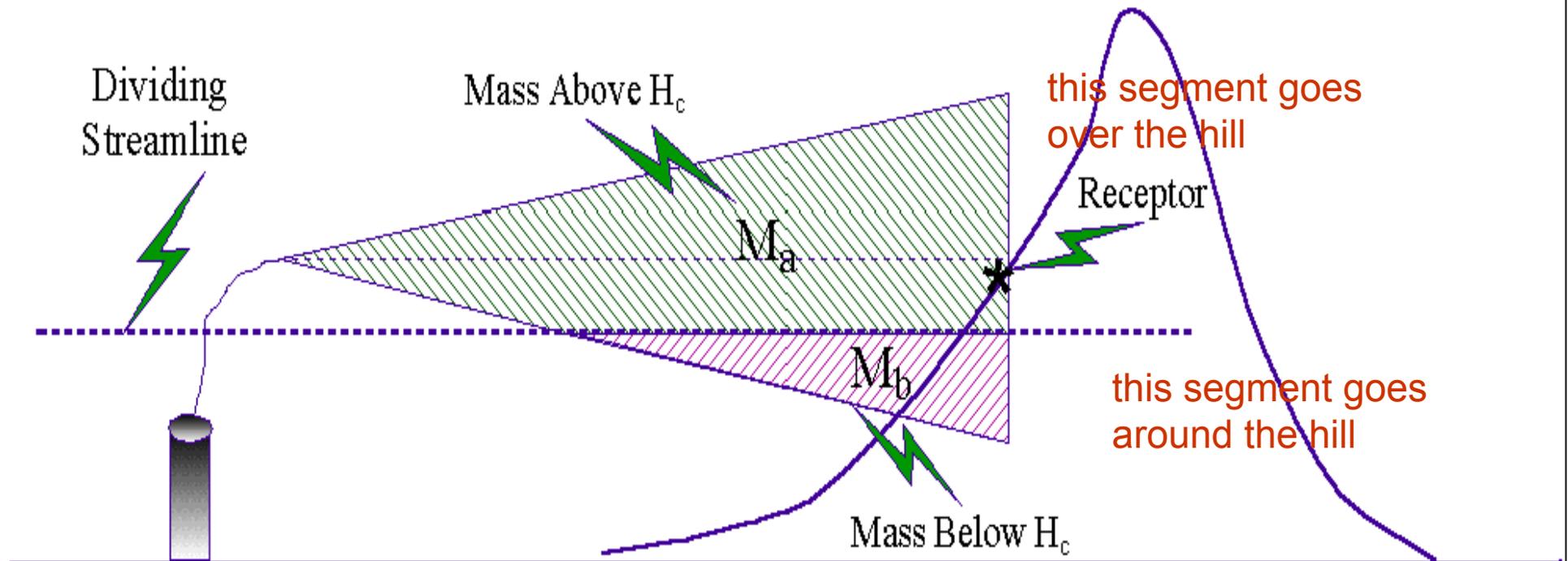


## **New 9. Steep terrain, building obstacles, land-use variations**

- Many advances here
- EPA complex terrain experiments and other hill experiments led to formulas for plume flow around and impaction on hills. The methods were incorporated in AERMOD and other models
- Building downwash and urban field studies led to improvements in some models
- TIBL studies for coastal plumes
- Still there is not a good objective way to account for land-use variations in operational models

# AERMOD Treatment of Hills - Assume Two Plume Segments (above and below $H_c$ )

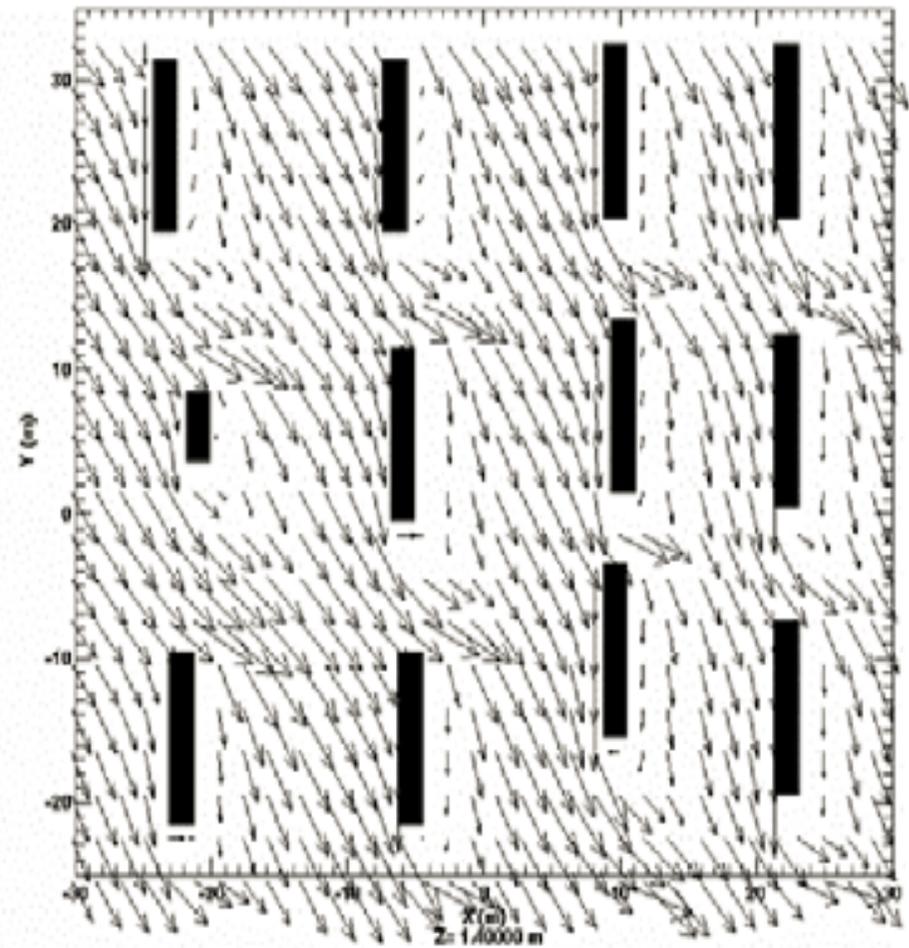
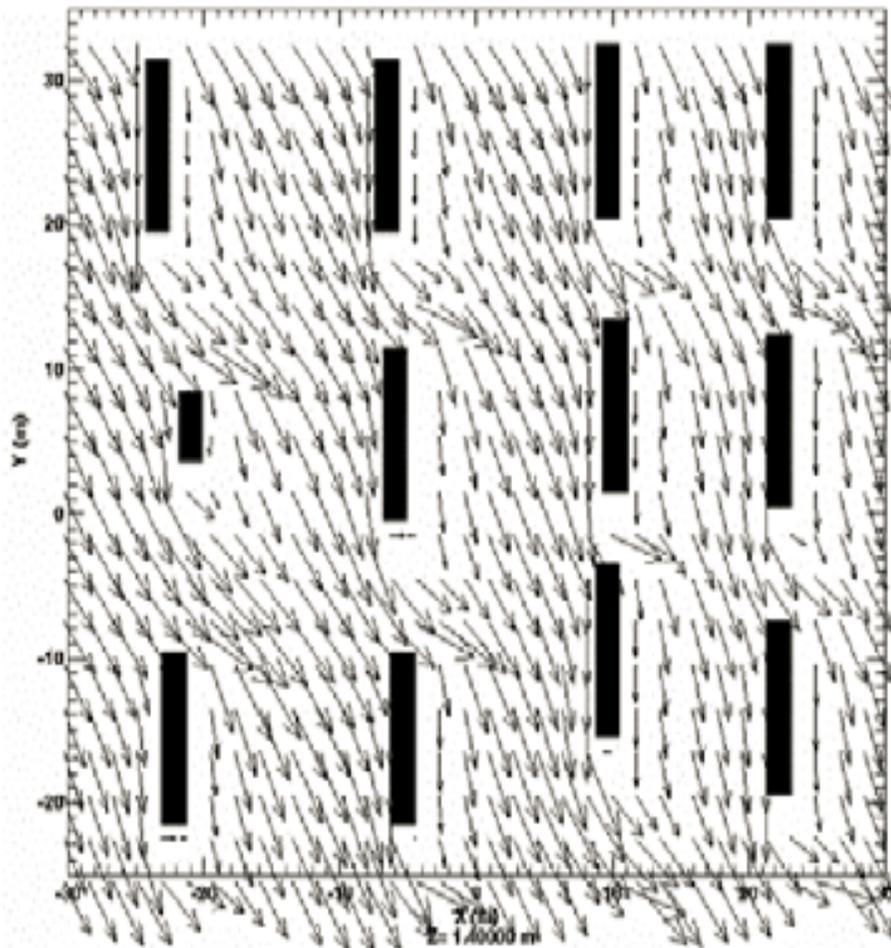
$$C_{\text{Tot}} = f C_{\text{Horiz}} + (1-f) C_{\text{TerrRes}}$$



## New 10. Is new technology helping?

- Since 1992 there have been many orders of magnitude increases in computer speed and storage
- Are our models orders of magnitude better? No. Maybe a factor of two better in evaluations with field data
- What happened? Natural variability of the atmosphere overwhelms the system
- CFD models – Slow, but can be used to parameterize operational models. Some persons use hybrid systems such as QUIC.
- WRF grid scale is always getting smaller. Lundquist et al. have a 1 m version applied to cities.

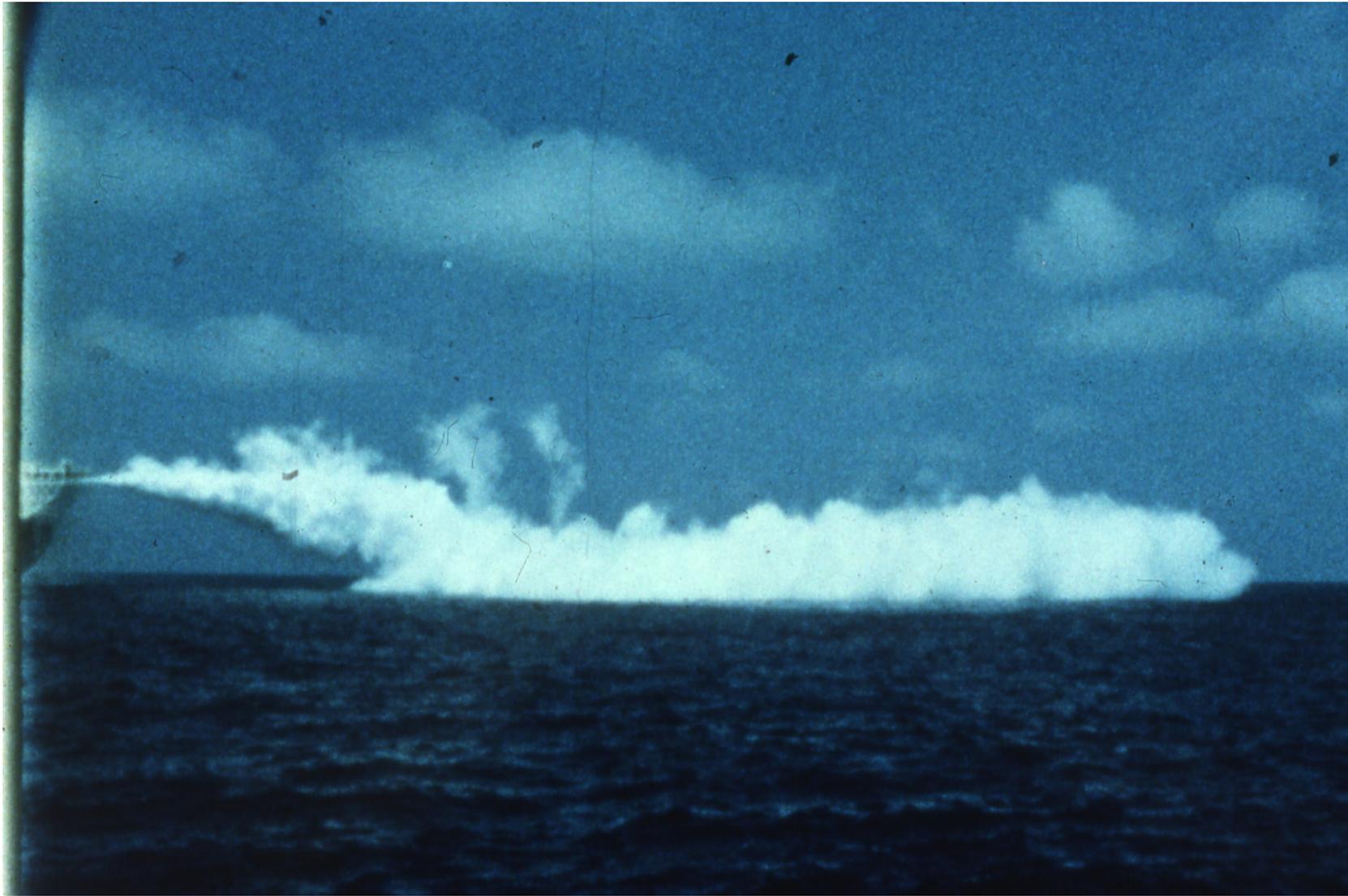
# RAMS flow simulations for part of the MUST obstacle array (Trini-Castelli and Reisin, 2010) for two k- $\epsilon$ schemes



# New 11. Dense plumes and chemical reactions

- Since 1992, there have been many studies and improvements in this area, mainly driven by emergency response and air pollution regulations
- Good dense gas models are available but are not in the USEPA regulatory arena
- Chemical reactions (and phase transitions) are in regional AQ models, and in some short-range models (such as SCICHEM). AERMOD uses simple parameterizations.
- Plume-in-grid models in regional AQ models like CMAQ.

## Release of LNG from back of tanker onto water



**“CLASSIC” Dense Cloud Behavior**

# Conclusions

- Many of the 1992 limitations are still of concern
- Sometimes research advances are not quickly adopted by operational models
- There are several new limitations
- Will 3-D Eulerian models eventually do everything as grid size reduces and computers improve?
- The atmosphere's natural variability causes problems in demonstrating improvements