

# Coupled Urban Outdoor and Indoor Synthetic Dispersion Environments

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A. Piña, G. Bieberbach, and D. Lorenzetti**

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# Outline

- **Background and enabling technology**
  - Motivation for a coupled urban and interior virtual CBRN environment
  - Virtual environment system design
  - Graphics processing unit (GPU) based atmospheric dispersion modeling
- **GPU-Large Eddy Simulation (LES) system validation effort**
- **GPU-LES system demonstration**
- **Looking forward**

# Outline

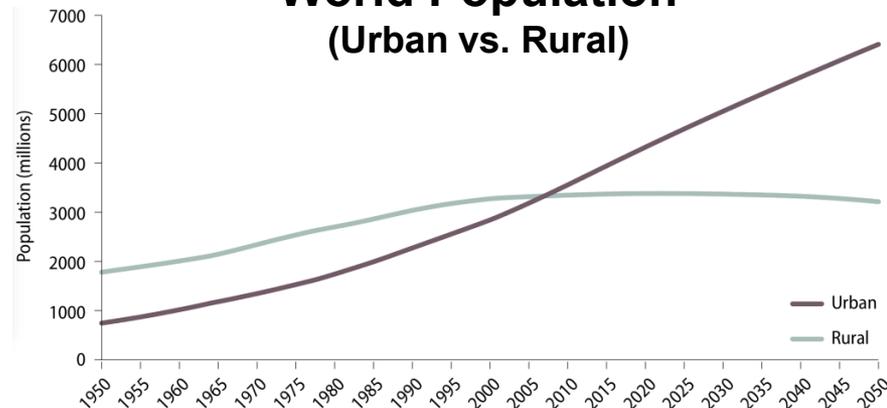
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# Indoor and Outdoor Air Quality

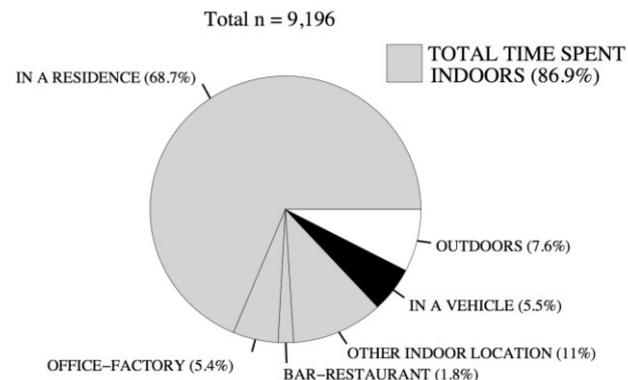
## (Importance of Coupling Indoor/Outdoor Dispersion Models)

- **Most of the world's population lives in urban locations**
  - In the US, > 80%
  - Urban populations are expected to continue to grow
- **People spend the majority of their time indoors**
  - In the US, > 86%
- **Urban - indoor environments are some of the highest impact locations for health effects from pollution**

**World Population  
(Urban vs. Rural)**



**U.S. National Human  
Activity Pattern Survey (NHAPS)  
(Nation – Percentage Time Spent)**



**Image Sources:**

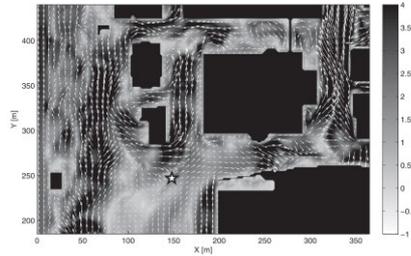
- [http://www.nhm.org/nature/sites/default/files/blog\\_images/urbanpop-edited.png](http://www.nhm.org/nature/sites/default/files/blog_images/urbanpop-edited.png)
- Klepeis NE, Nelson WC, Ott WR et al., 2001: The National Human Activity Pattern Survey (NHAPS): A Resource for Assessing Exposure to Environmental Pollutants. *Journal of Exposure Analysis and Environmental Epidemiology*. 11(3):231-252.



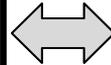
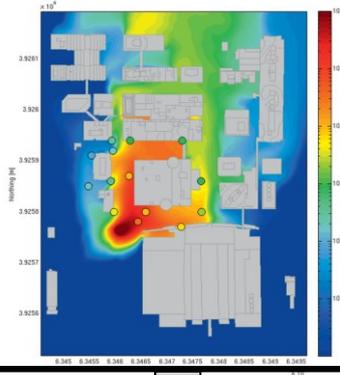
# Urban and Outdoor Pollution Dispersion Models (Virtual Environment System Design)

## Urban Outdoor Virtual Environments

### Winds and Turbulence

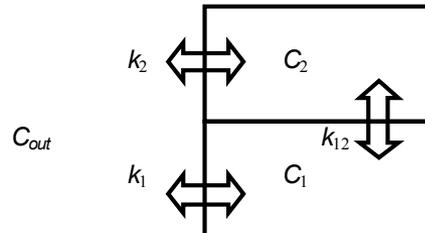


### CB Concentrations

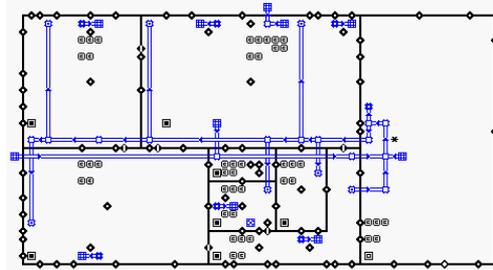


## Indoor Virtual Environments

### Analytical Models



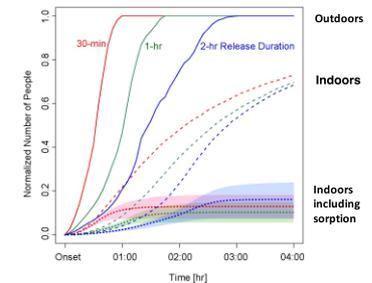
### Multi-zone Models



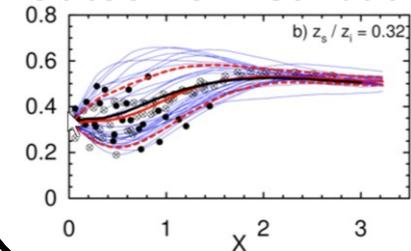
## Air Quality Analysis Outcomes

### Individual Scenario Consequence

Population Experiencing Serious Health Effects (Exceeding AEGL2)



### Outcome Distribution

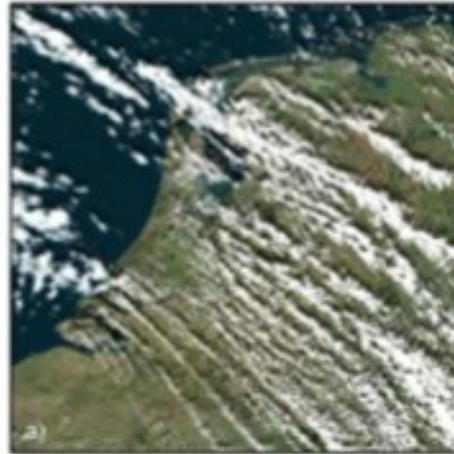
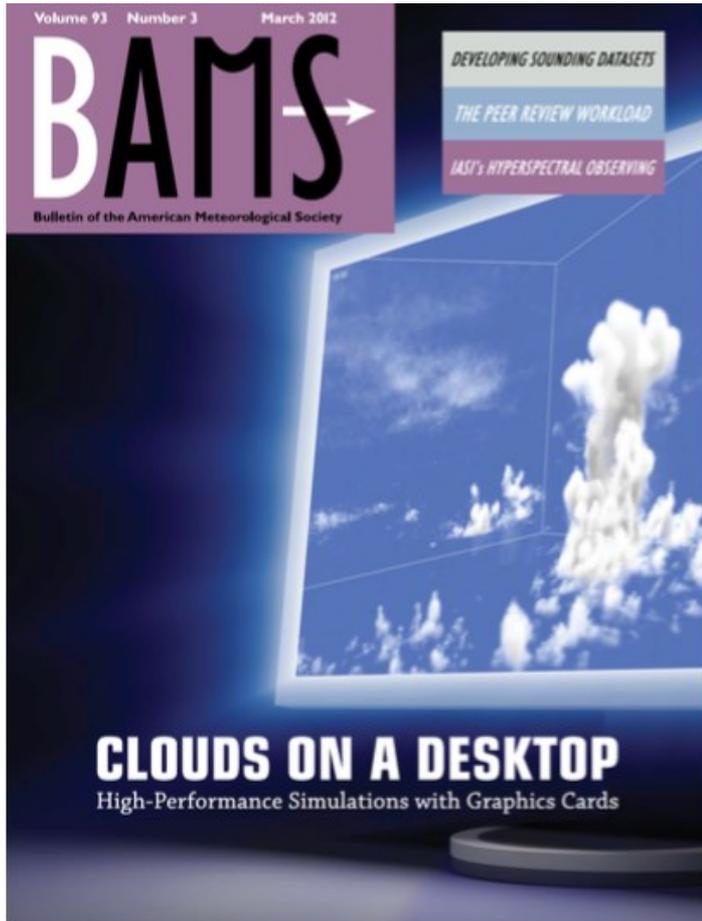


Use Improve Our Understanding of Indoor-Outdoor Contaminant Exchanges

Image sources: - Lundquist, K.A., F.K. Chow, and J.K. Lundquist, 2012: An immersed boundary method enabling large-eddy simulations of flow over complex terrain in the wrf model. *Mon. Wea. Rev.*, **140**, 3936–3955  
 - Jeff Weil, "Evaluation of a GPU-Based Large-Eddy Simulation for Dispersion in the Atmospheric Boundary Layer", Presented at the AMS - 19th Conference on Applications of Air Pollution Meteorology, 10-14 January, 2016

# Enabling Technology

## (GPU Resident Atmospheric Simulation Program (GRASP))

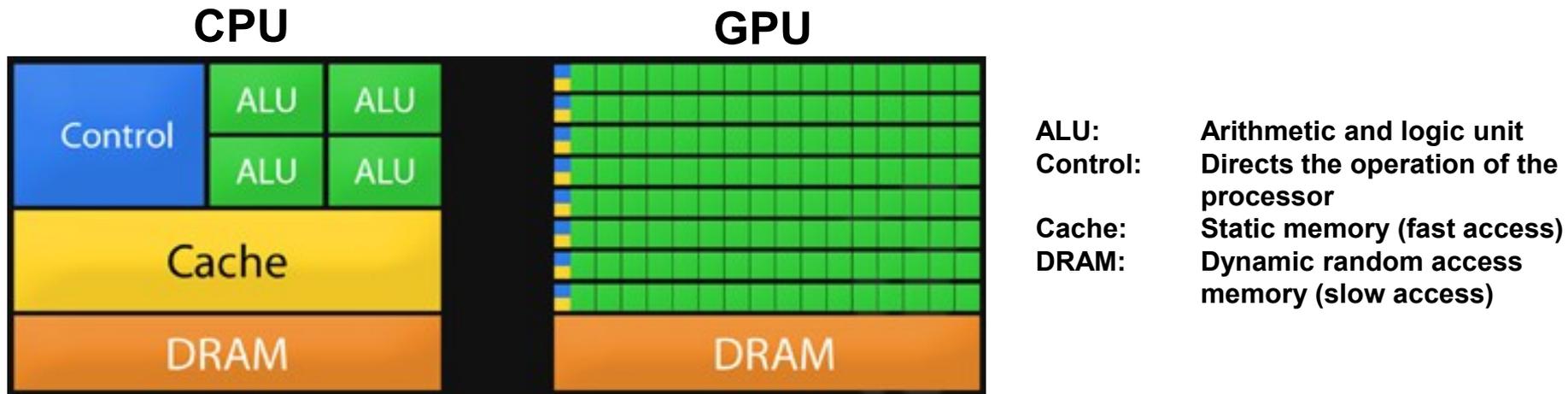


**WHIFFLE**  
WEATHER FINECASTING

**Publications:** Schalkwijk et al. *BAMS* 2012  
 Schalkwijk et al. *MWR* 2015  
 Schalkwijk et al. *BAMS* 2015  
 Schalkwijk et al. *BLM* 2016

# Enabling Technologies

(Background on GPU and CPU Hardware Designs)



- **CPU is optimized to perform sequential operations**
  - Multiple ALU's (cores) enable some parallel performance
  - Typically has a large cache memory availability compared to GPU
- **GPU is optimized to perform highly parallel operations**
  - Numerous ALU's (1000's on a single GPU card)
  - Faster and more advanced memory interfaces
  - Currently in a phase of rapid hardware technology advancements

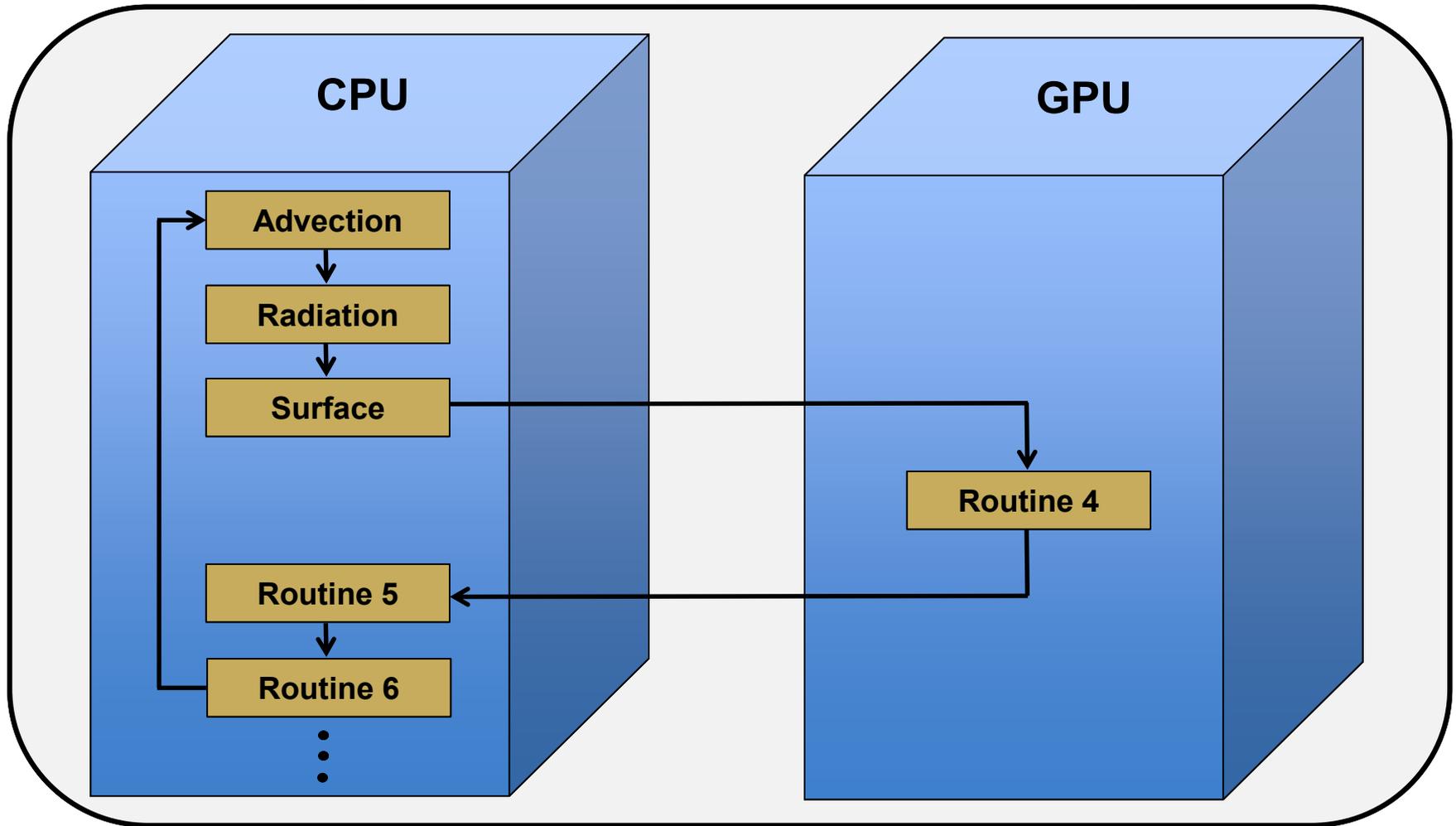
Image Source: - [http://www.frontiersin.org/files/Articles/70265/fgene-04-00266-HTML/image\\_m/fgene-04-00266-g001.jpg](http://www.frontiersin.org/files/Articles/70265/fgene-04-00266-HTML/image_m/fgene-04-00266-g001.jpg)



# Atmospheric Modeling

(Past Practices for “GPU-Accelerated” HPC Computing)

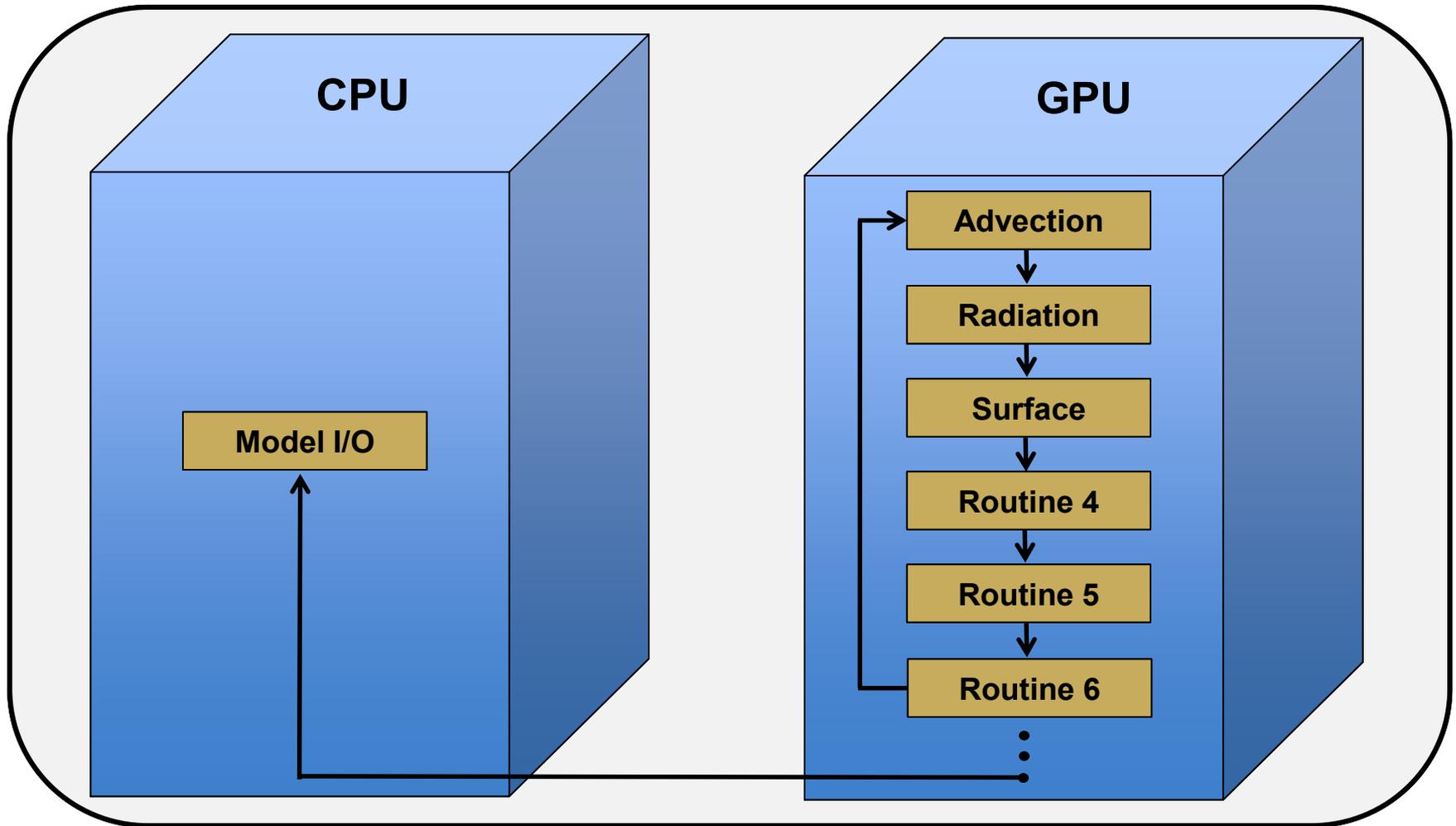
## Atmospheric Modeling on a CPU/GPU Computer



# Atmospheric Modeling

(Next Generation of GPU HPC Computing)

## GPU Resident Modeling



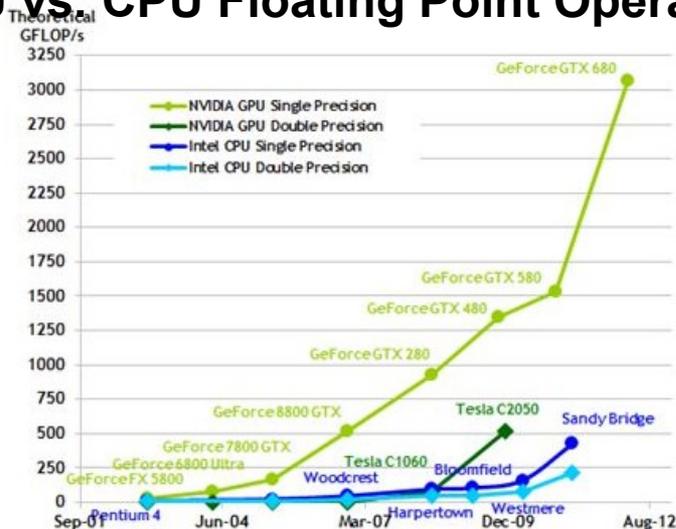
Returning us to a “Shared-Memory” Computing Paradigm

# This Technology Enables

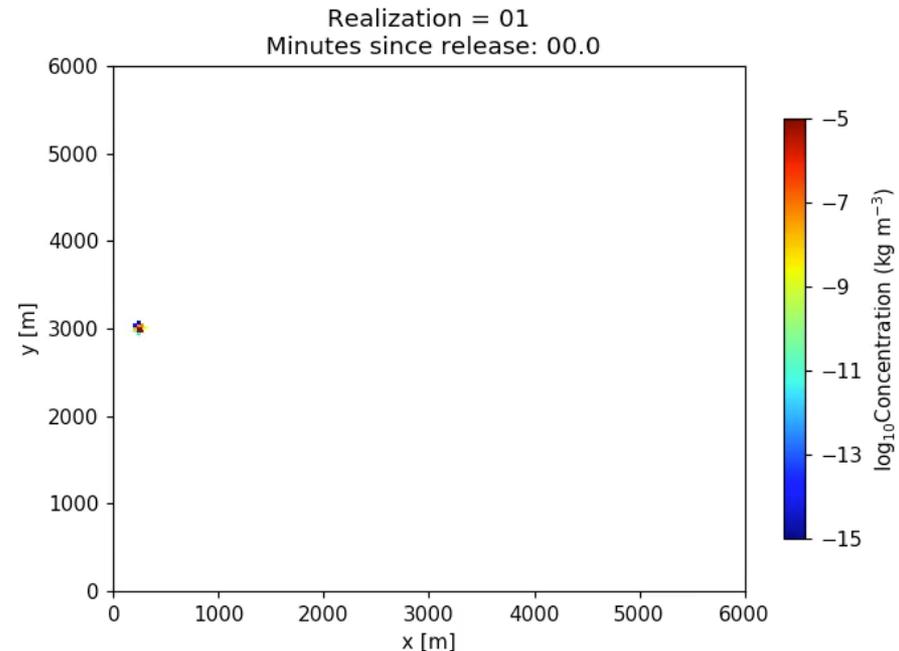
(Ensembles of Single Realization Dispersion Solutions)

- GPU provides substantial computational advantage over comparable CPU-based solution
- Example: 1-hr simulation
  - 8 core Intel Xenon: 1hr 32 mins
  - Nvidia K40: 36 seconds
- Rapid technology advances

## GPU vs. CPU Floating Point Operations



## Puffs Released Into Unstable Outdoor Conditions



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# GPU-LES Dispersion Model System Validation

(Incremental Approach From More Simple to More Complex)

- **Meteorological validation: *Completed***
- **Open terrain atmospheric transport and dispersion (AT&D): *In process***
  - Completed for unstable boundary layer
  - Neutral and stable boundary layer are in process
- **“Building aware” meteorology and AT&D: Collecting data sets and developing simulations**
  - Mock urban setting test (MUST)
  - 2015 Jack Rabbit II urban container testing (JR11-2015)
  - Joint Urban 2003 (JU2003)
- **Indoor-outdoor contaminant transport: No activity yet**



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# Open Terrain Validation

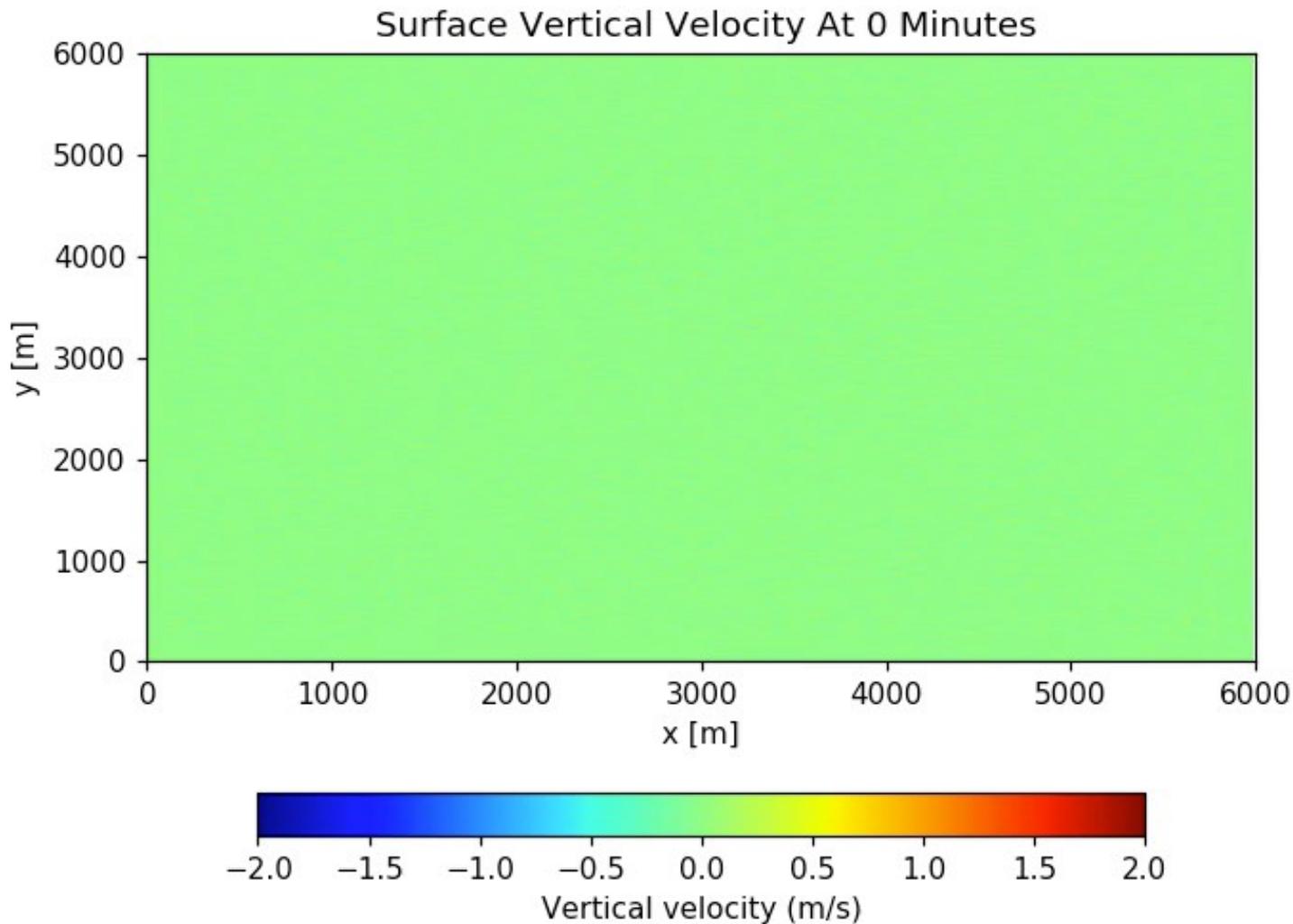
## (Model Simulation Design)

- **GPU-LES configuration patterned after Weil et al. 2004 & 2012**
  - Horizontal resolution: ~50 m vertical resolution: ~20 m
  - Domain: ~13 x ~13 km x ~2 km (*Larger than Weil et al. 2004*)
  - CBL depth: 1 km and heat flux =  $0.24 \text{ m s}^{-1} \text{ K}$
  - Wind Speed:  $\sim 3 \text{ ms}^{-1}$  in convective boundary layer
- **Release characteristics**
  - Continuous near surface point release
  - 130 uncorrelated realizations produced
  - Time and space differences used to create the realizations
- **Dispersion characteristics examined**
  - Plume height normalized by the boundary layer height
  - Surface crosswind integrated concentration (CWIC)
  - Vertical profiles of CWIC
  - Surface crosswind dispersion
  - Vertical dispersion



# Open Terrain Validation (Model Simulation Design)

Allow the Turbulence to Spin Up in the Model

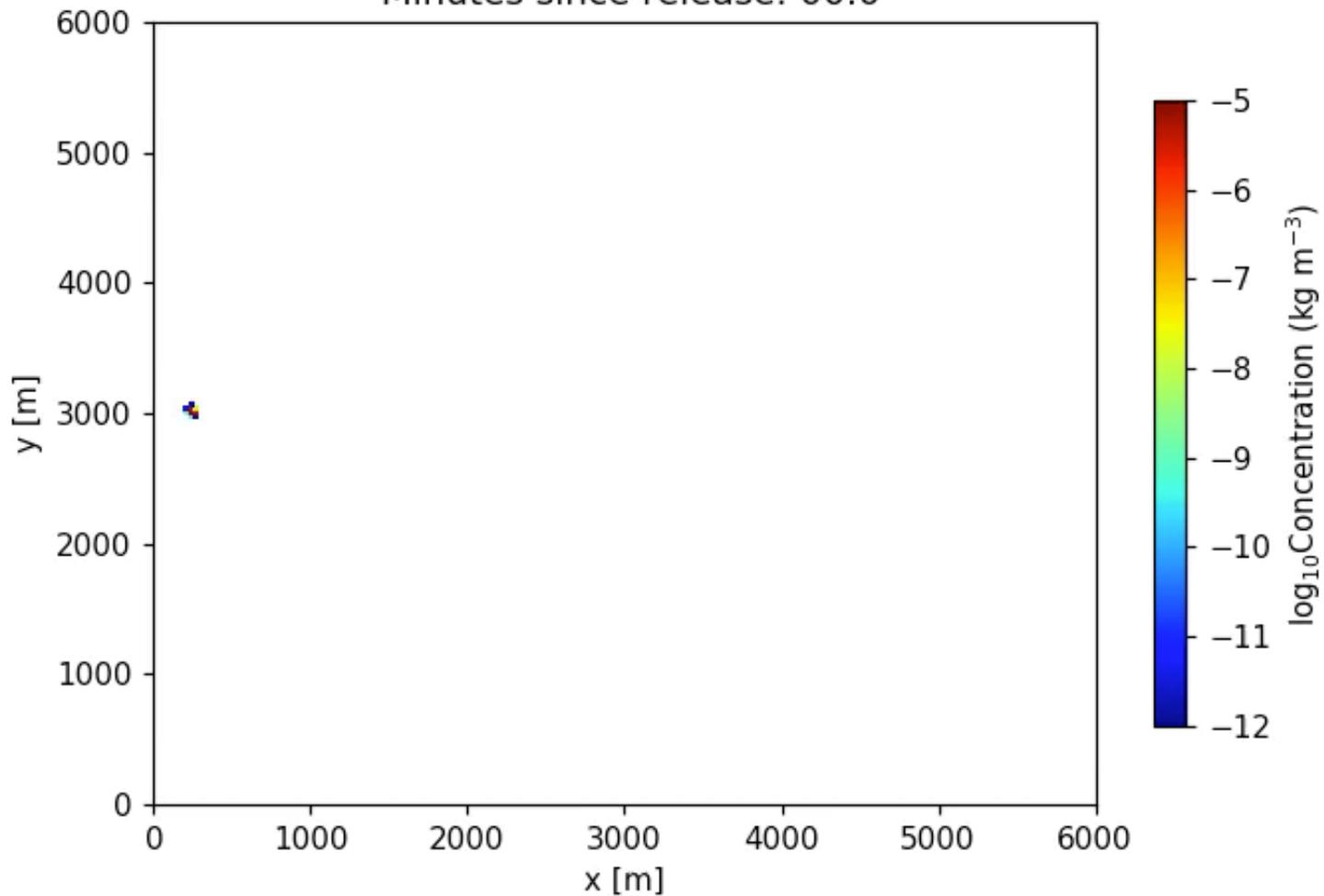


# Open Terrain Validation (Model Simulation Design)

## Create Uncorrelated Dispersion Realizations

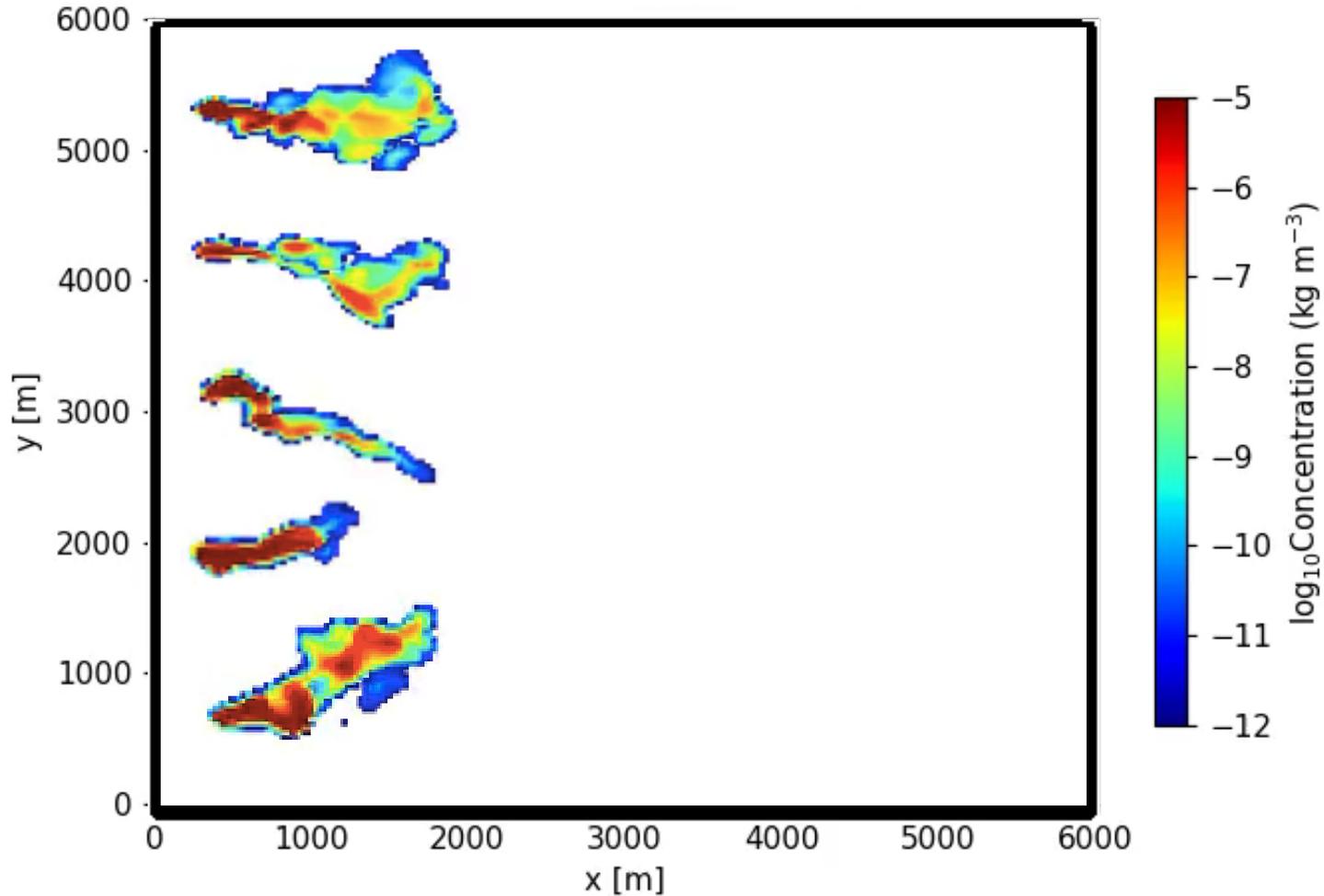
Realization = 01

Minutes since release: 00.0

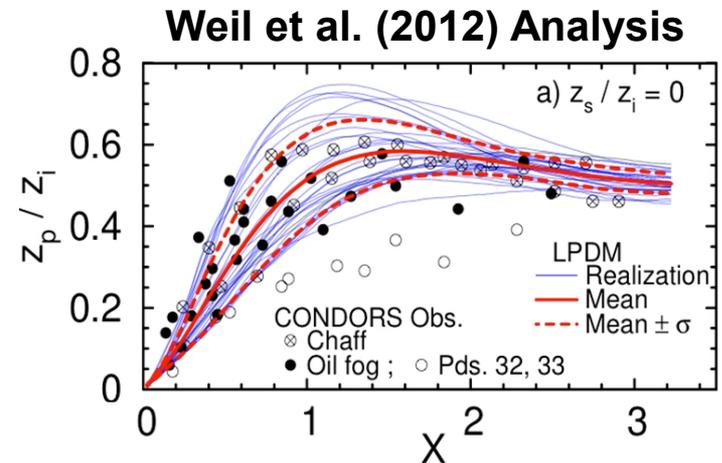
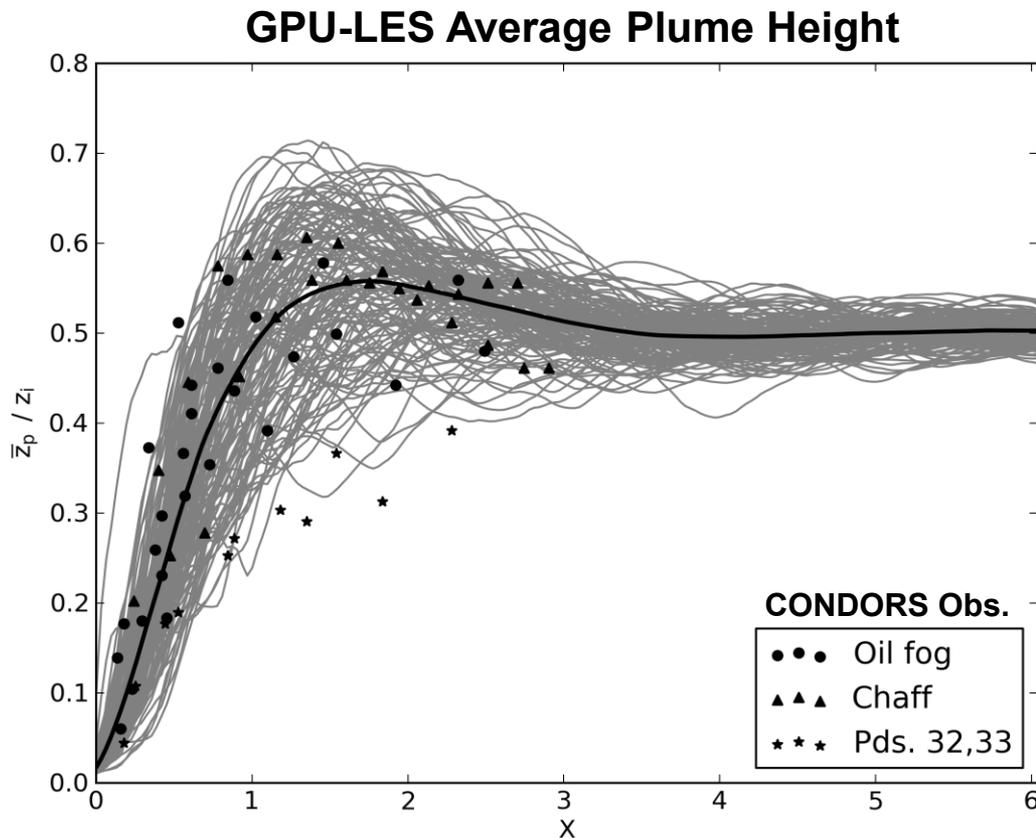


# Open Terrain Validation (Model Simulation Design)

Create Uncorrelated Dispersion Realizations  
(Example – 6 Minutes After Start of Release)



# Open Terrain Validation (Plume Height Calculations)



**Dimensionless  
Downwind Distance**

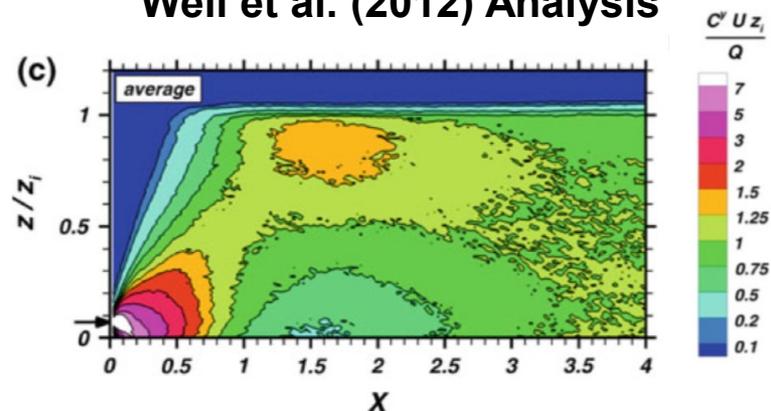
$$X = \frac{w_* x}{U z_i}$$

Image Source: Weil, J.C., P.P. Sullivan, E.G. Patton, C. Moeng, 2012: Statistical Variability of Dispersion in the Convective Boundary Layer: Ensembles of Simulations and Observations. *BLM*, **145**, 185–210

# Open Terrain Validation

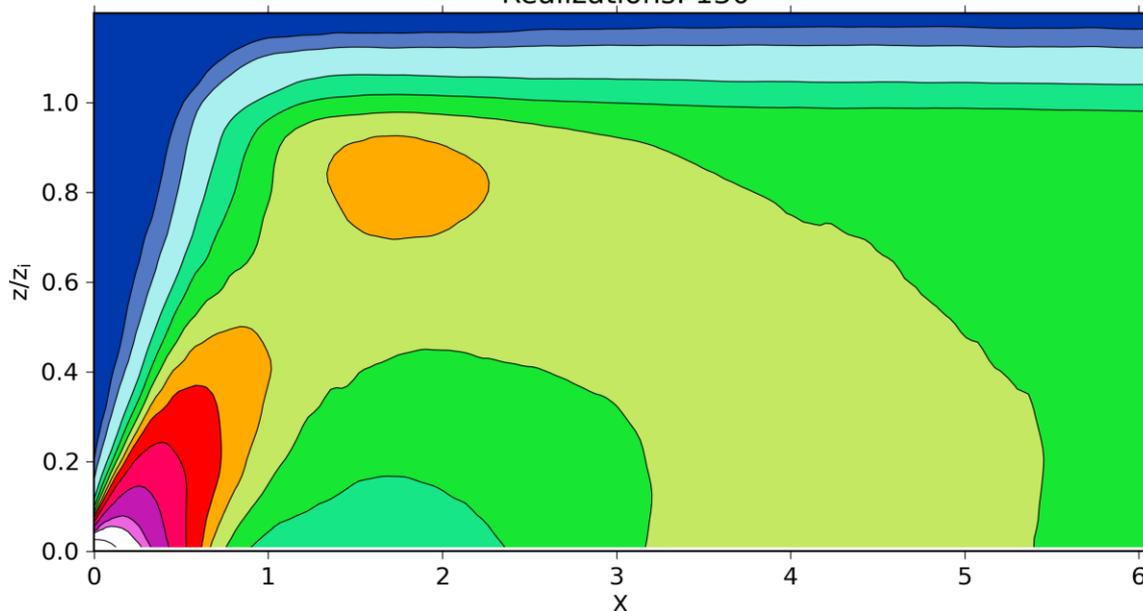
## (Cross Wind Integrated Concentration (CWIC) Calculations)

Weil et al. (2012) Analysis



### GPU-LES Average CWIC

Realizations: 130



**Dimensionless  
Downwind Distance**

$$X = \frac{w_* x}{U z_i}$$

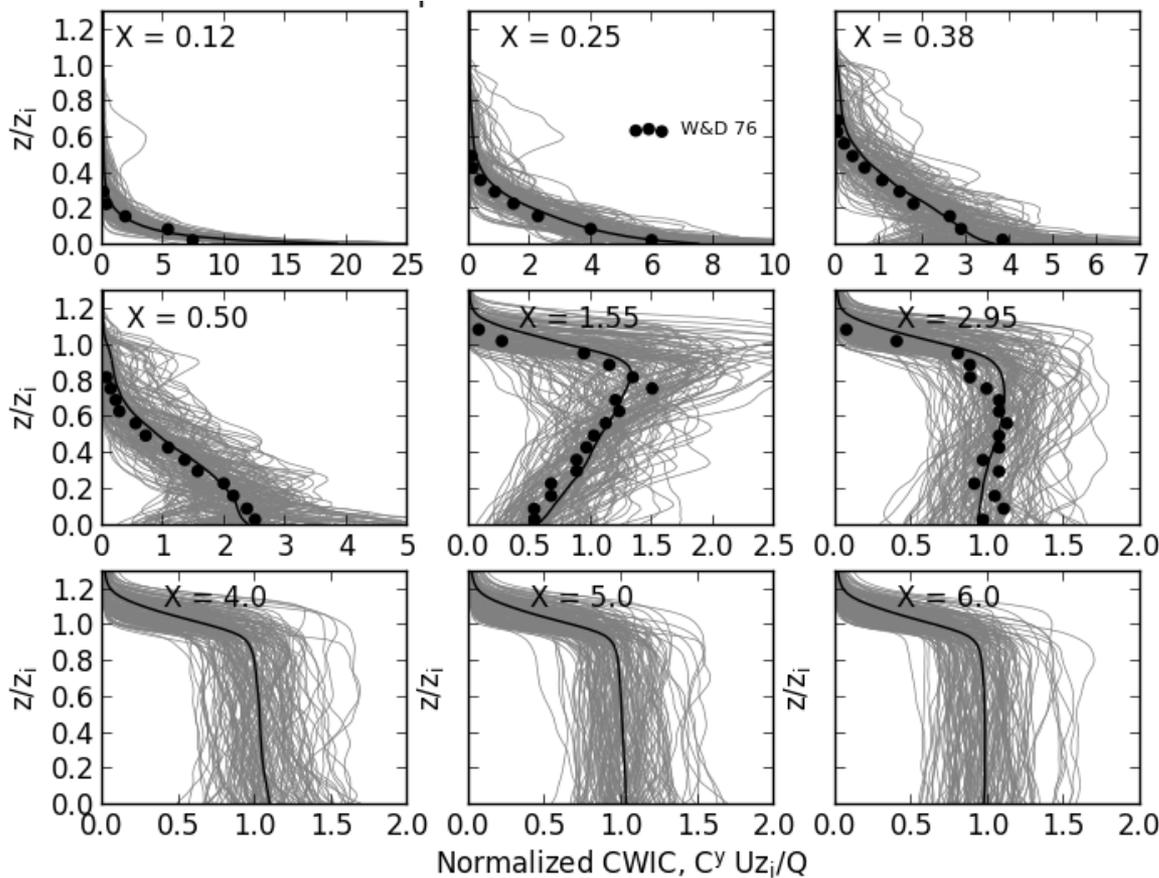
**Concentration**

$$CWIC = \frac{C^y U z_i}{Q}$$

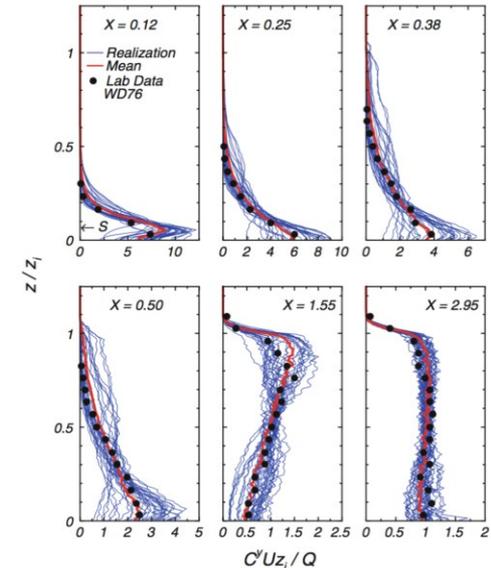
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# Open Terrain Validation (CWIC Vertical Profile Calculations)

## GPU-LES Vertical Profiles of CWIC



## Weil et al. (2012) Analysis



**Dimensionless  
Downwind Distance**

$$X = \frac{w_* x}{U z_i}$$

**Concentration**

$$CWIC = \frac{C^y U z_i}{Q}$$

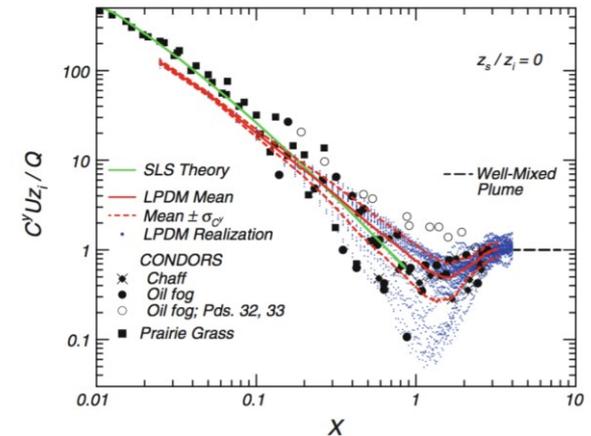
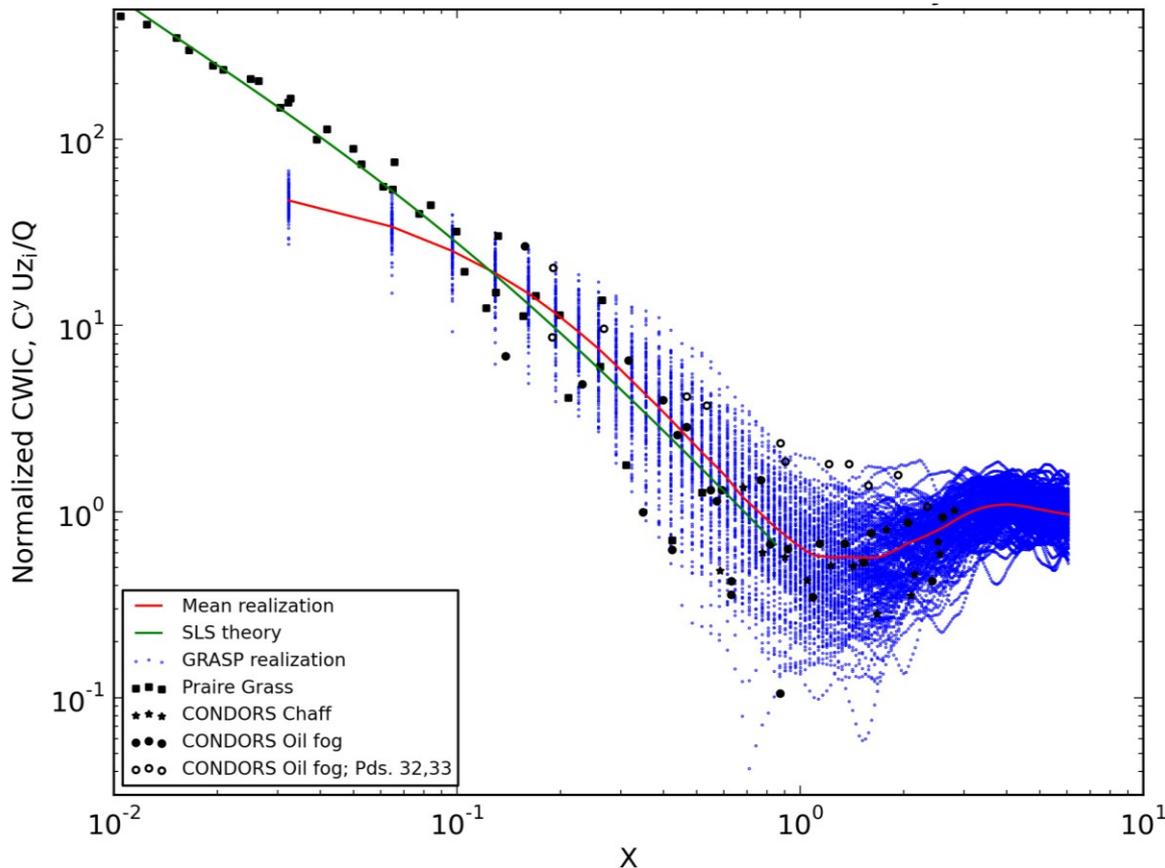
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# Open Terrain Validation

## (Surface Cross Wind Integrated Concentration (CWIC) Calculations)

Weil et al. (2012) Analysis

### GPU-LES Surface CWIC



**Dimensionless  
Downwind Distance**

$$X = \frac{w_* x}{U z_i}$$

**Concentration**

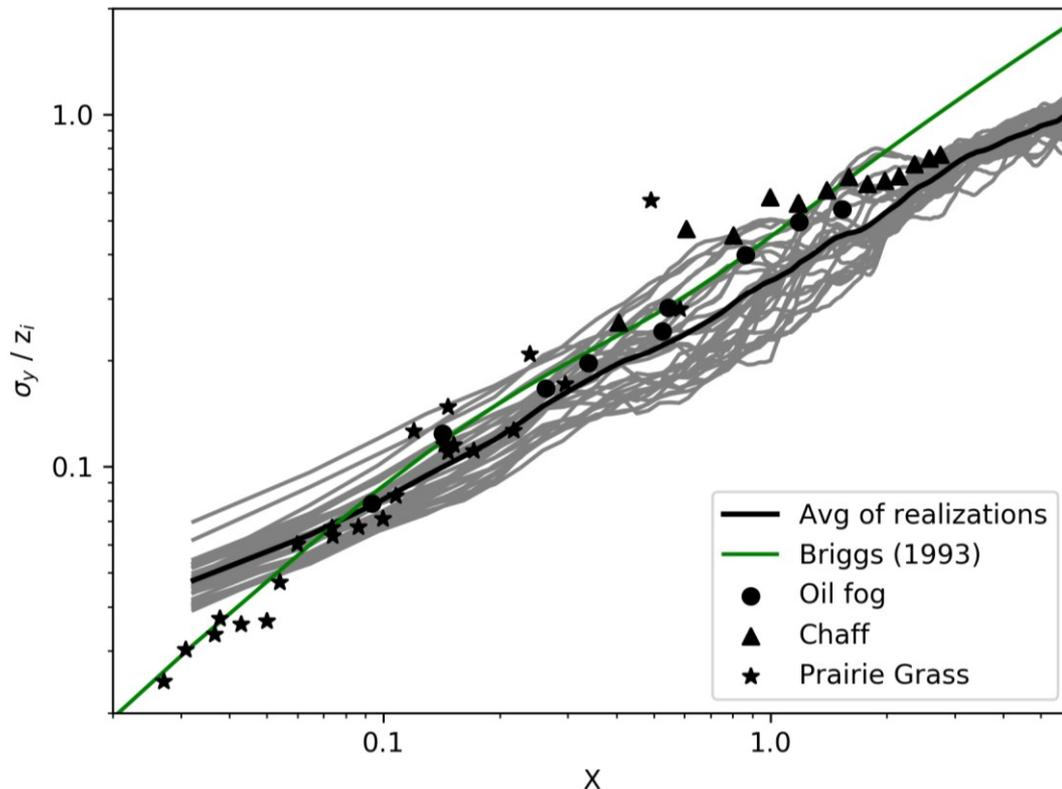
$$CWIC = \frac{C^y U z_i}{Q}$$

Image Source: Weil, J.C., P.P. Sullivan, E.G. Patton, C. Moeng, 2012: Statistical Variability of Dispersion in the Convective Boundary Layer: Ensembles of Simulations and Observations. *BLM*, **145**, 185–210

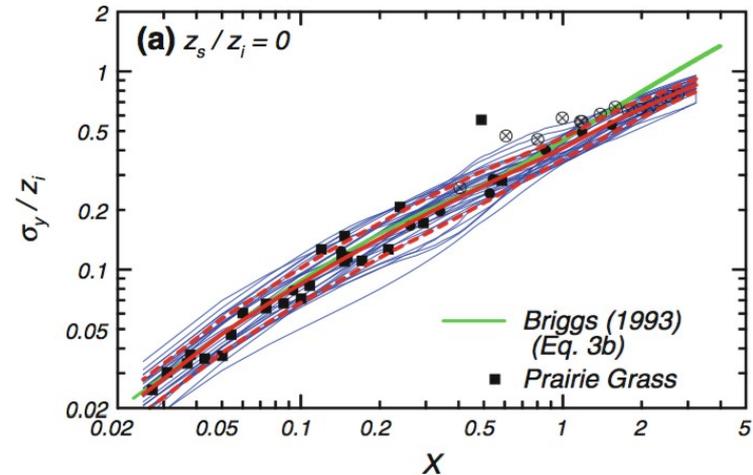
# Open Terrain Validation

## (Surface Cross Wind Dispersion Calculations)

### GPU-LES Surface Cross Wind Dispersion



### Weil et al. (2012) Analysis



**Dimensionless  
Downwind Distance**

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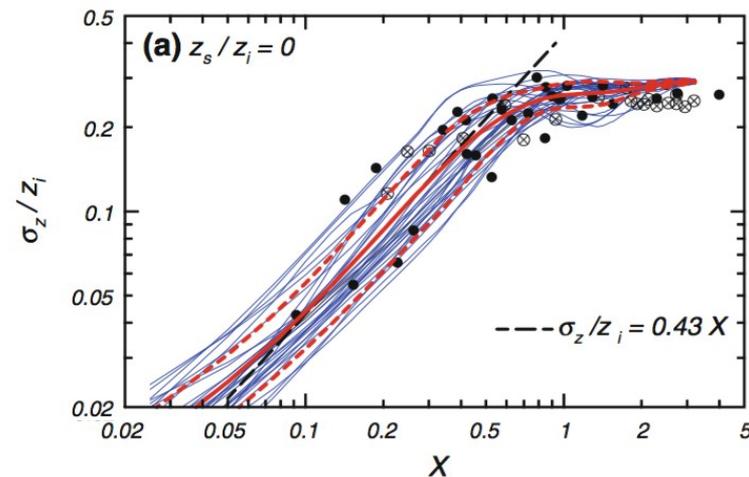
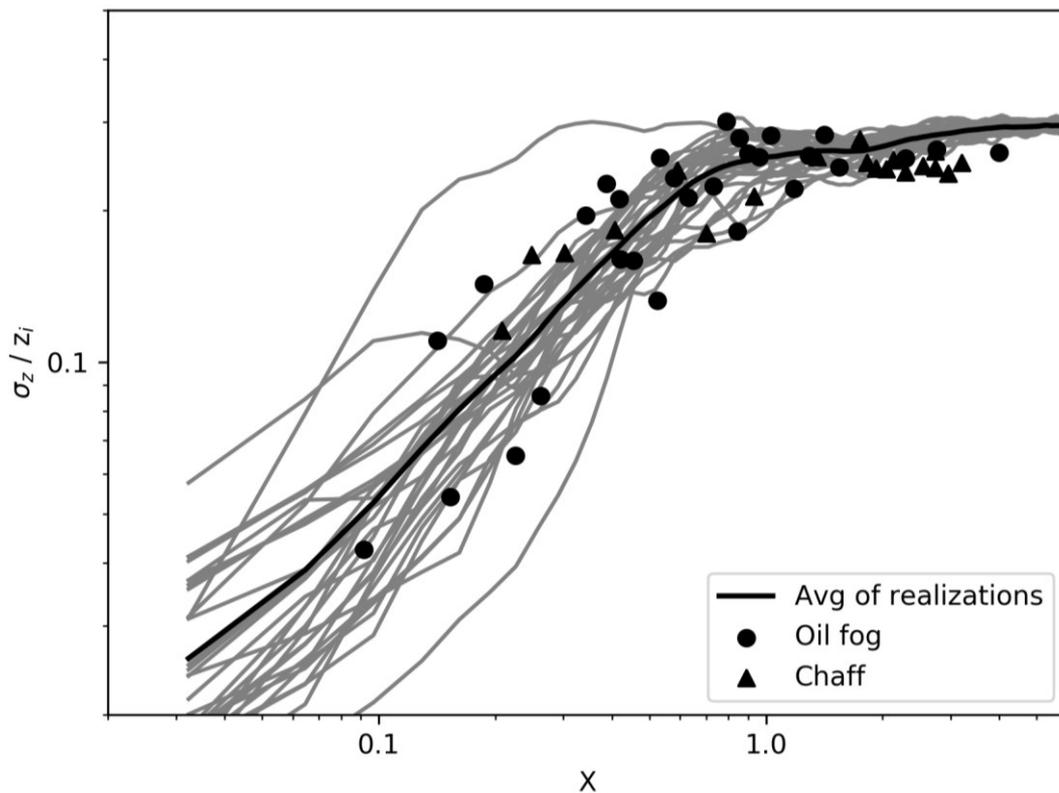
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# Open Terrain Validation

## (Surface Vertical Dispersion Calculations)

Weil et al. (2012) Analysis

### GPU-LES Vertical Dispersion



**Dimensionless  
Downwind Distance**

$$X = \frac{w_* x}{U z_i}$$

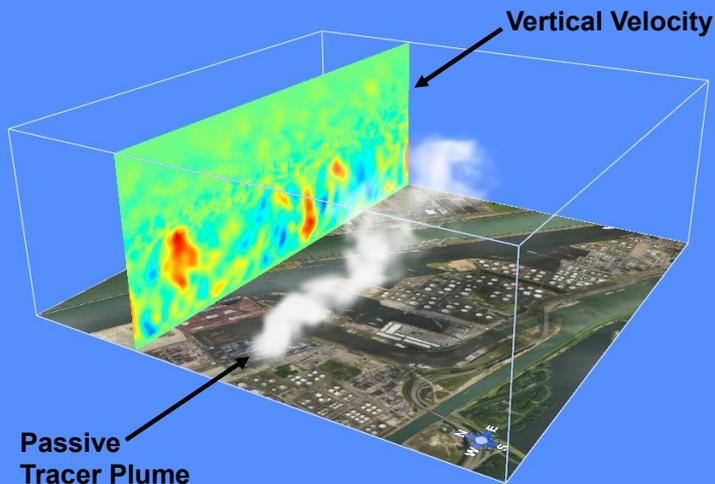
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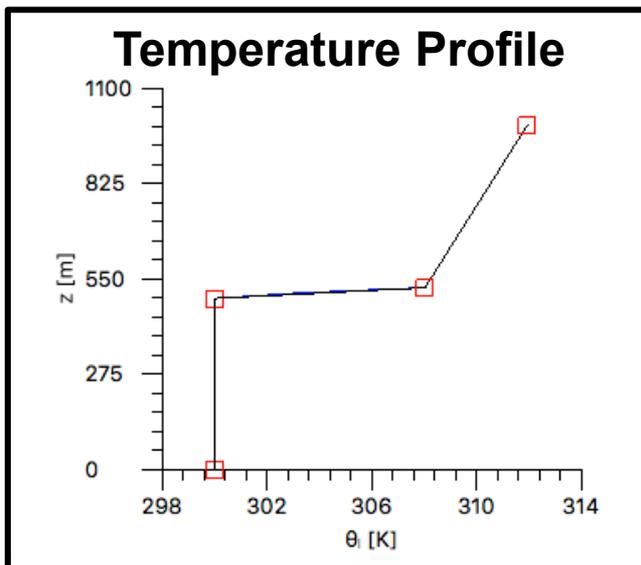
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# Demonstration

## (Open Terrain Example)



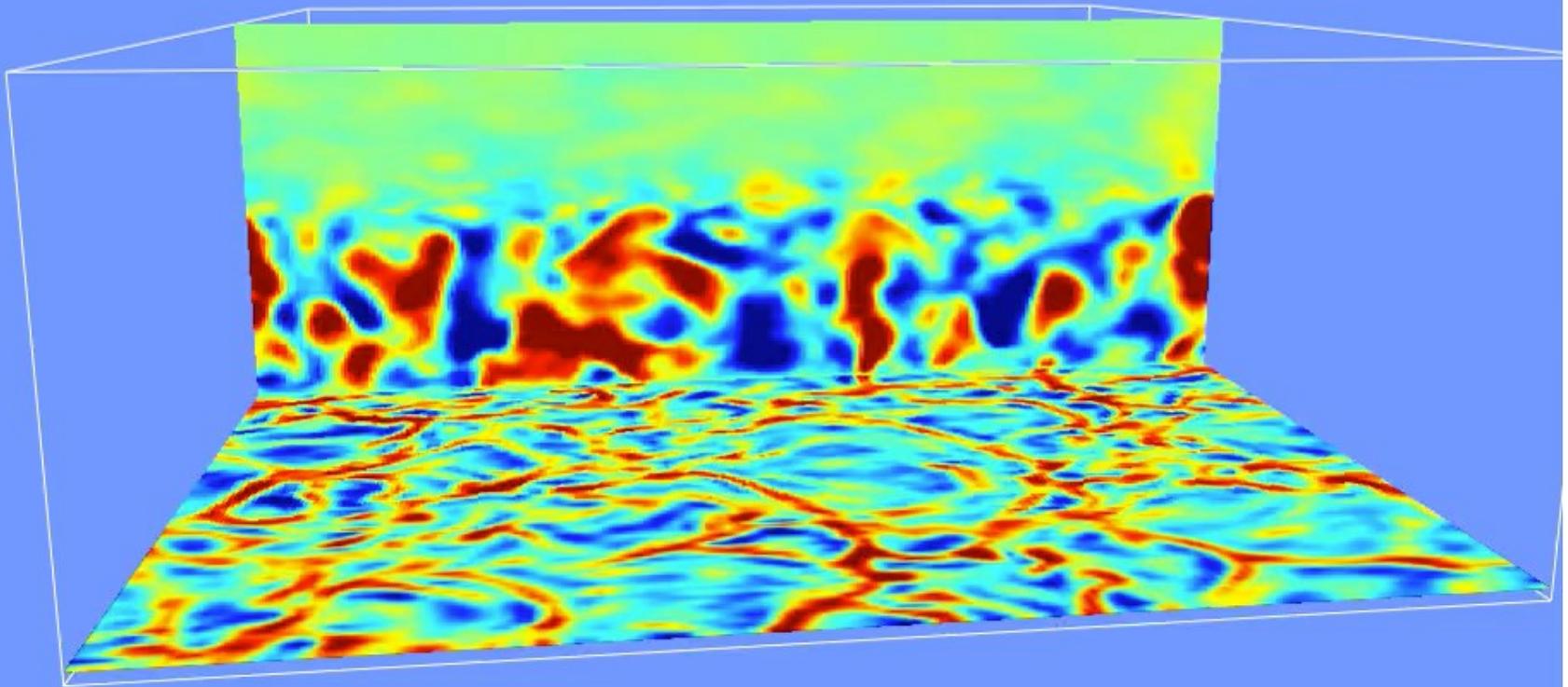
- **Open terrain simulation specifications**
  - 128 x 128 x 64 grid
  - Horizontal resolution: 20 m
  - Vertical resolution ~17 m
- **Simulation scenario**
  - Boundary layer (BL) depth: 550 m
  - Surface heating: 50 W/m<sup>2</sup>
  - Winds:
    - 3 m/s in PBL
    - 4 m/s above PBL
- **Simulation time on NVIDIA K40**
  - 2880 ALU cores
  - 12 Gb of onboard memory
  - 1-hr simulation takes ~ 36s



# Demonstration

(Open Terrain Example)

09:11

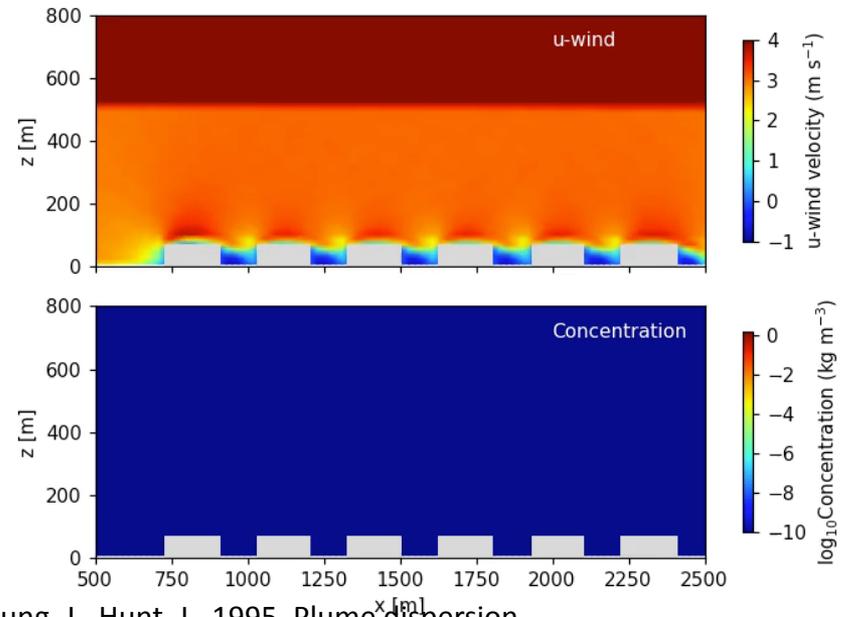
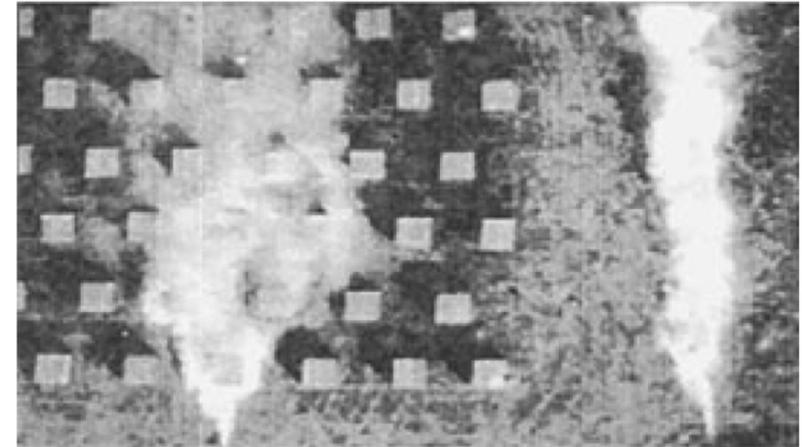
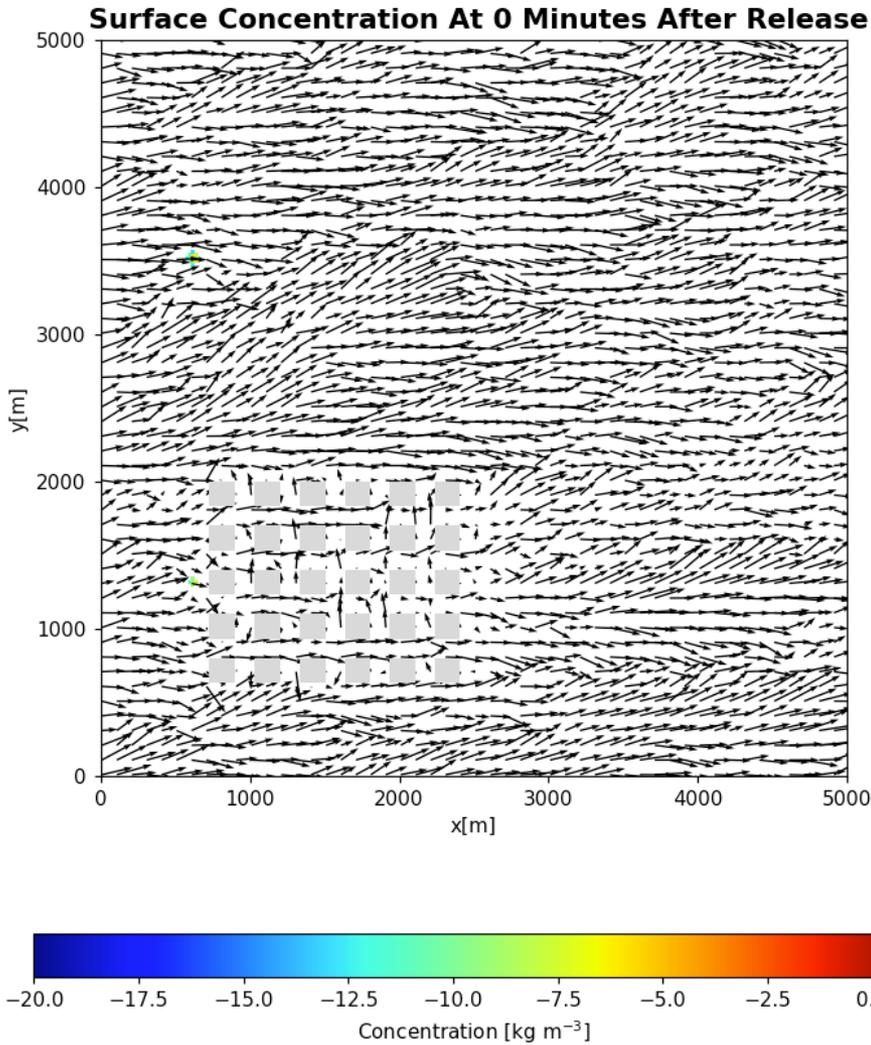


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# Looking Forward (Incorporation of Buildings)

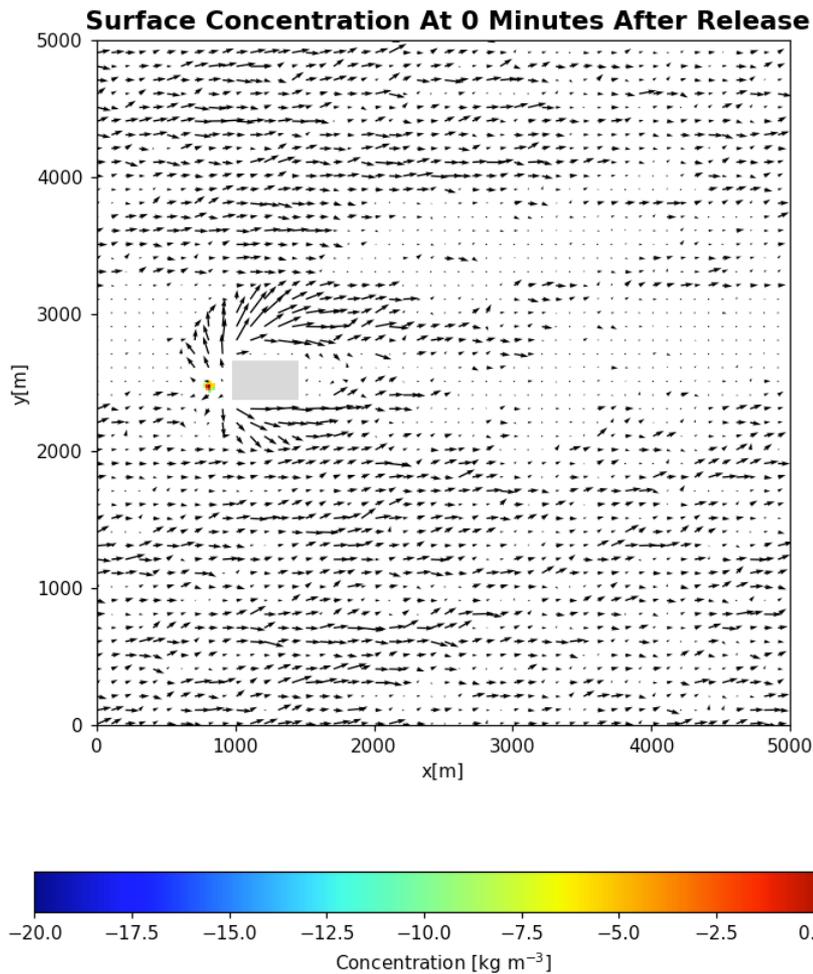
## Davidson et al. (1995) Experiment



**Image Source:** Davidson, M., Mylne, K., Jones, C., Phillips, J., Perkins, R., Fung, J., Hunt, J., 1995. Plume dispersion through large groups of obstacles e a field investigation. Atmos. Environ. 29, pp. 3245-3256.

# Looking Forward

## (Linking the Indoors to the Outdoors)



### Two Zone Box Model

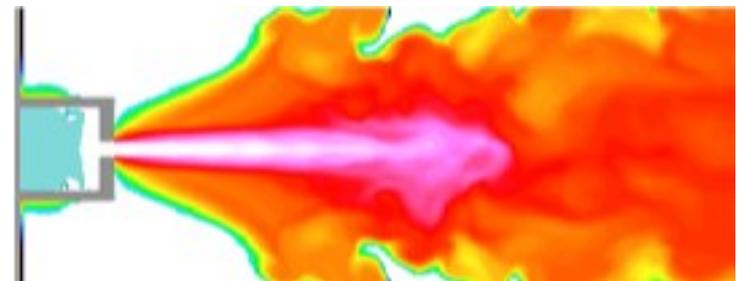
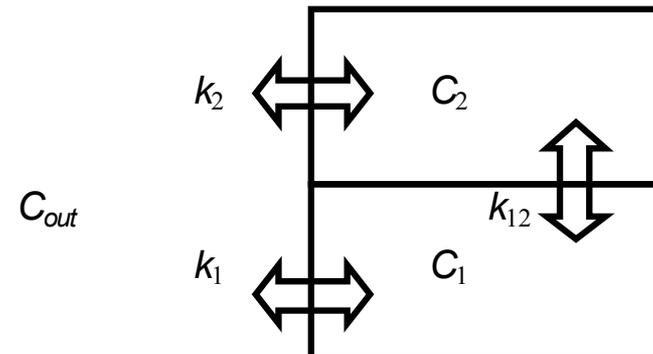
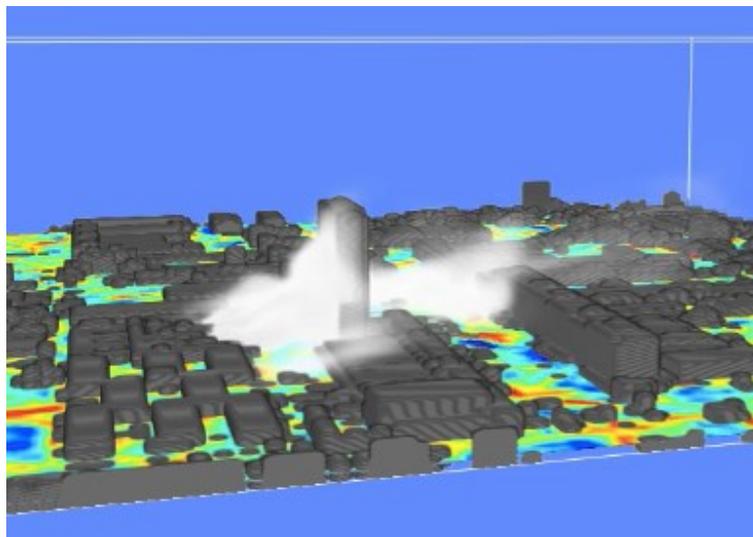


Image Courtesy of Darrel Johnston SWRI – 2015

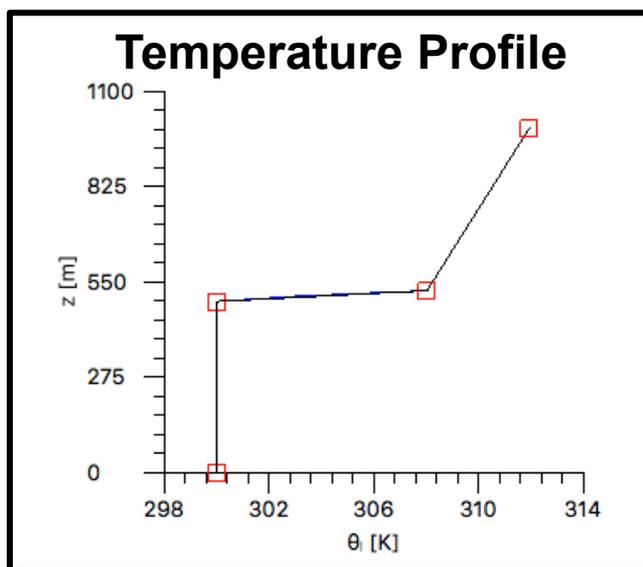


# Demonstration

## (Building Aware Example)



- **“Building-aware” terrain simulation specifications**
  - 256 x 256 x 128 grid
  - Horizontal resolution: ~4 m
  - Vertical resolution ~8 m
- **Simulation scenario**
  - Boundary layer (BL) depth: 550 m
  - Surface heating: 25 W/m<sup>2</sup>
  - Winds:
    - ~3 m/s in PBL
- **Simulation time**
  - 2880 ALU cores
  - 12 Gb of onboard memory
  - 1-hr simulation takes ~ 155s



# Demonstration

(Building Aware Example)

08:28

